

### DP3254 16 Channel 32 scans Low-turning PWM Constant Current Driver

## **1** Overview

DP3254 Is a 16-channel low-transition PWM constant current drive chip designed for LED display. The high-precision current generating circuit technology is integrated, the current error between the chips can be controlled within 2.0%, and the low gray high brush mode is added to improve the low gray refresh rate. And integrated with a variety of exclusive technology to improve the display effect of the LED display, which can bring more improvements to the display screen.

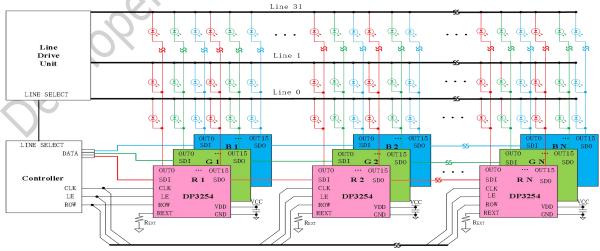
## 2 Features

- Power supply voltage range: 2.6~5.5V
- Operating temperature range: -40°C ~85°C
- Scan range: 1~32 scan, any adjustable
- 16 constant current output channels
- Support for no external resistance mode
- Constant flow output range
  - $0.5mA \sim 18mA$  (V<sub>out</sub>=0.3V)
  - $0.5 \text{mA} \sim 25 \text{mA}$  (V<sub>out</sub>=0.45V)
- Inter-channel current error
  - Typical value: ± 1.2% Maximum value: ± 2.5% (V<sub>out</sub>=0.45V)
- Inter-chip current error
  - Typical value: ± 1.5% Maximum value: ± 2.0%
- High gray independent refresh, no black field between frames
- Low gray and high brush: low gray supports 1~8 times display frame rate
- The imum refresh rate supports 128 times

- frame rate (7680Hz)
- Optimize the display status
  - Improve the low-gray uniformity
  - Improve the first line of partial darkness phenomenon
  - Improve the phenomenon of the ghost shadows
  - Improve the high and low grey coupling
  - Improve cross-plate coupling
- Integrated PLL produces in-house GCLK with a lower EMI
- Packaging form: QSOP24 / QFN 24
- Excellent ESD features

# **3 Application Fields**

- High refresh rate LED video display
- One color two color full color LED display
- High-density small-spacing LED light board display



DP3254 A Schematic diagram of the typical application

#### www.depuw.com

德普微电子

**DP3254** DP3254 16 Channel 32 scans Low-turning PWM Constant Current Driver

## catalogue

1 Overview1
2 Features1
3 Application Fields1
4 Product Description5
5 Circuit Schematic Diagram6
5.1 Input-output equivalent circuit6
5.2 Internal Circuit Block Diagram7
6 Parameter List8
6.1 Maximum Limit Parameter8
6.2 ESD Grade 8
6.2.1 Contact ESD8
6.3 Electrical Characteristics (VDD=3.5V~5V,
Ta=25℃)9
6.4 Dynamic Characteristics (VDD=3.5V~5V,
Ta=25℃)11
Ta=25°C)11 7 Test Circuit Diagrams13
Ta=25°C)
Ta=25°C)
Ta=25°C)
Ta=25°C)
Ta=25℃)11         7 Test Circuit Diagrams13         7.1 Test Circuit 113         7.2 Test Circuit 213         7.3 Test Circuit 315
$Ta=25^{\circ}C$ )       11         7 Test Circuit Diagrams       13         7.1 Test Circuit 1       13         7.2 Test Circuit 2       13         7.3 Test Circuit 3       15         7.4 Test Circuit 4       15
$Ta=25^{\circ}C$ )       11         7 Test Circuit Diagrams       13         7.1 Test Circuit 1       13         7.2 Test Circuit 2       13         7.3 Test Circuit 3       15         7.4 Test Circuit 4       15         7.5 Test Circuit 5       16
$Ta=25^{\circ}C)$ 11         7 Test Circuit Diagrams       13         7.1 Test Circuit 1       13         7.2 Test Circuit 2       13         7.3 Test Circuit 3       15         7.4 Test Circuit 4       15         7.5 Test Circuit 5       16         7.6 Test Circuit 6       16
$Ta=25^{\circ}C$ )       11         7 Test Circuit Diagrams       13         7.1 Test Circuit 1       13         7.2 Test Circuit 2       13         7.3 Test Circuit 3       15         7.4 Test Circuit 4       15         7.5 Test Circuit 5       16         7.6 Test Circuit 6       16         7.7 Test Circuit 7       17

5
8.1.2 Inter-channel Current Error
8.2 Constant Flow Source linflection Point
8.3 Adjust The Output Current By Using The
External Resistance20
8.4 The No-resistance Mode Adjusts The Current
By A Register20
9 Typical Display Effect Pattern
9.1 Display Effect21
9.1.1 Remove The Open Circuit Break Point
Cross
9.1.2 High and Low Gray Interference and
Coupling Display Bad Effect Optimization 21
9.1.3 Remove Ghostiness and Bandless Lighting
Effects
10 Directive and Register24
10.1 Register Instructions24
10.2 Data Command24
10.3 Single/Double Mode Switch24
10.4 Write Register26
10.5 Sending Mode of the Register Signal
10.6 The ROW Signal Transmission Mode27
10.7 The PWM Display Mode
10.7.1 General Frame Synchronization Mode. 29
10.7.2 High Gray Data Refresh Frame
Synchronization Model Independently
10.7.3 High-gray data Independently Refreshes
Asynchronous Mode29

www.depuw.com

#### DP3254



DP3254 16 Channel 32 scans Low-turning PWM Constant Current Driver

10.7.4 Low-grey and High-brush Mode
0.8 Relevant Configuration of PWM Display 30
10.8.1 Row Scan Number Configuration
10.8.2 Line gray-scale Series Configuration 30
10.8.3 PWM Display Packet Configuration30
10.8.4 Internal Grayscale Clock Configuration 30
10.8.5 PWM Gray Series & Gamma Generation31

10.7.4 Low-grey and High-brush Mode	10.8.6 Calculated the Display Time for Each
8 Relevant Configuration of PWM Display 30	Row31
10.8.1 Row Scan Number Configuration	10.9 Open Circuit Detection and Removal of Bad
10.8.2 Line gray-scale Series Configuration 30 10.8.3 PWM Display Packet Configuration 30 10.8.4 Internal Grayscale Clock Configuration 30 10.8.5 PWM Gray Series & Gamma Generation 31	Spots
	13 Encapsulation information    37      14 Official Announcement    39
Developer Microeler	tionics

2023/11/14 3 www.depuw.com DP3254 REV0.3 EN The content of the document is a trade secret, without permission, any organization or individual shall not copy and spread in any form!



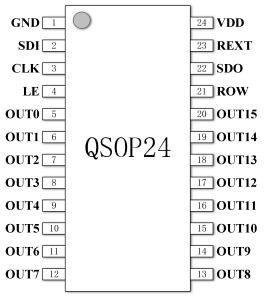
德晋微电子 DP3254 DP3254 16 Channel 32 scans Low-turning PWM Constant Current Driver

### Revise the history

edition	Revised date	Revised	Revised content
V 0.1	2023.07	Wang Mei	The initial version
V0.2	2023.08	Wang Mei	Modify the instructions and the registers
V0.3	2023.11	Wang Mei	Modify the QFN encapsulation pin definitions
	eveloper		Selectronics

## **4** Product Description

The pin definition



QSOP24 Pin definition diagram

CLK REXT ROW SDO VDD SDI 19 18 23 21 20 24 22 **OUT15** LE 1 OUT0 17 **OUT14** 2 OUT1 3 16 **OUT13** QFN24 OUT2 4 15 **OUT12** OUT3 5 14 **OUT11 OUT10** OUT4 13 6 10 11 12 OUT8 0UT9 **OUT7** GND OUT6 **OUT5** 

The QFN 24 pin definition diagram

Feet instructions

QSOP24 Pin	The QFN 24 pin	Feet name	Feet instructions
number	number		
1	10	GND	Chip ground end
2	23	SDI	Serial data input side
3	24	CLK	Serial clock input end
4	1	LE	The latch end of the data and instructions, and different LE lengths represent different instructions
5~20	2~9 11~18	OUT0 ~ OUT15	Constant flow output
21	20	ROW	Change the line signal
22	19	SDO	Serial data output side
23	21	REXT	Connect external resistance
24	22	VDD	Chip power end

#### Product order information

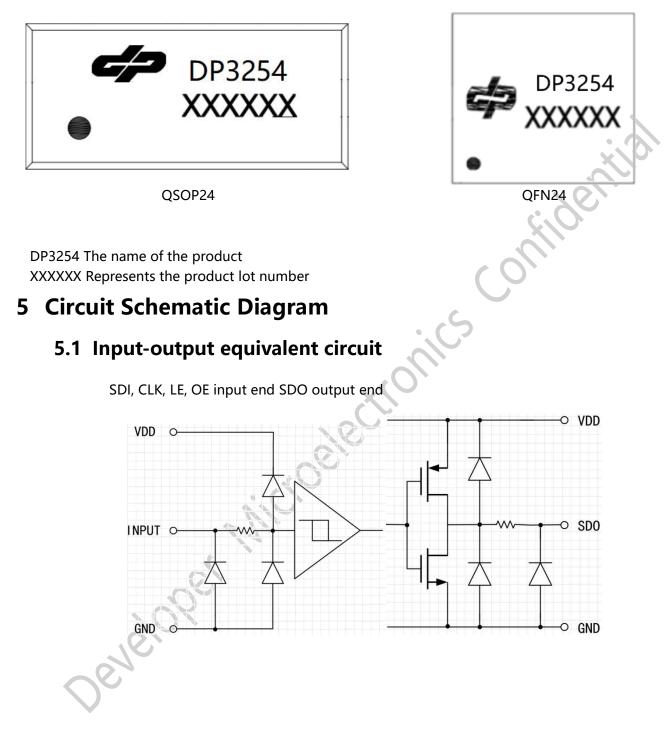
product name	Packaging form	manner of packing	Quantity / plate	Wet sensitivity level
552254	QSOP24	braid	4000	
DP3254	QFN24	braid	5000	MSL=3

2023/11/14

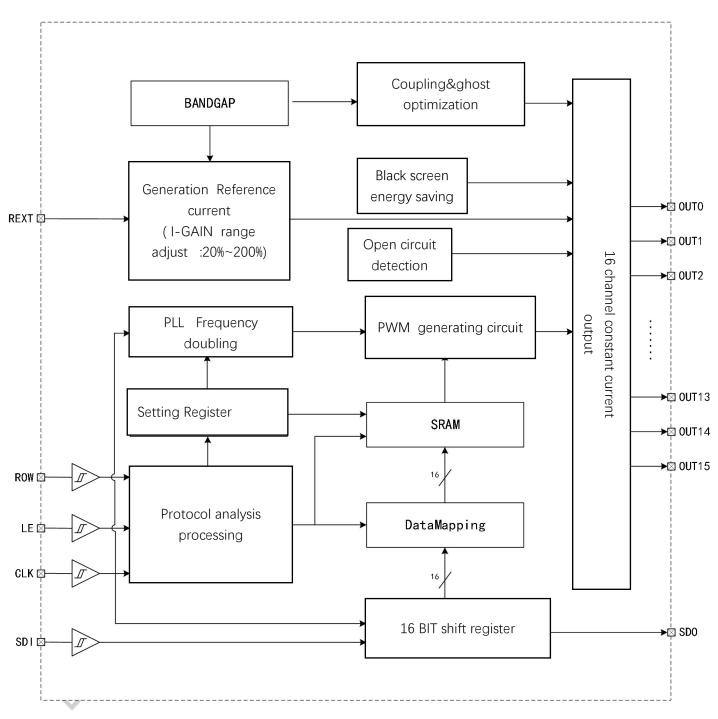
DP3254 REV0.3 EN

www.depuw.com

Product marking



## 5.2 Internal Circuit Block Diagram



A Schematic diagram of the internal circuit

### 6 Parameter List

#### 6.1 Maximum Limit Parameter

微甲子

project	symbol	rating	unit
supply voltage	V <sub>DD</sub>	0 ~ 5.5	V
output	Ι <sub>ο</sub>	25	mA
input voltage	V <sub>IN</sub>	-0.4 ~ V <sub>DD</sub> +0.4	v
Output tolerance voltage	V <sub>OUT</sub>	11	V
clock frequency	F <sub>CLK</sub>	25	MHz
working temperature	T <sub>opr</sub>	<del>c</del> .O	-
Storage temperature	T <sub>stg</sub>	-55 ~ 150	°C

All the voltage values are based on the chip ground end (GND) as the reference point, and the test temperature of the maximum limit parameter is 25°C.

- The actual working conditions exceeding the specified value may cause permanent damage to the components; the actual working conditions falling slightly below the maximum value and working for long hours may reduce the reliability of the components. The above is only partially specified values, and this product does not support functional operation under other conditions than the specification.
- The highest welding temperature of the table paste product shall not exceed 260°C. The temperature curve shall be set by the factory according to the J-STD-020 standard, refer to the actual factory and the manufacturer of the tin paste.

### 6.2 ESD Grade

#### 6.2.1 Contact ESD

symbol	C	ondition	least value	represent ative value	crest value	unit
	Human Discharge	OUTn Pin-GND	-	-	-	kV
V	Model (HBM) <sup>1</sup>	OTHER Pin-GND	-	-	-	kV
V <sub>(ESD)</sub>	machine model	OUTn Pin-GND	-	-	-	kV
(MM) <sup>2</sup>		OTHER Pin-GND	-	_	_	kV

[1] The lowest HBM model ESD voltage of all the pins meets the Class-3B standard in the JEDEC JS-001-2017 file.

[2] The lowest MM model ESD voltage of all pins meets the Class-C standard for the JEDEC EIA / JESD22-A115C file.

DP3254



## 6.3 Electrical Characteristics (VDD=3.5V~5V, Ta=25°C)

proje	ect	symbo	test	test condition		least	repres entati	crest	unit
proje		I	circuit			value	ve value	value	
		VR_TT			V <sub>DD</sub> =5V,R <sub>EXT</sub> =1K IGAIN=100%,T <sub>a</sub> =25℃		1.533		V
REXT vo	ltago	VR_LT		$V_{DD}=5V$	T <sub>a</sub> =-40°C	-	1.56	<u> </u>	V
characte	-	VR_HT	1	R <sub>EXT</sub> =1K IGAIN=100%	T <sub>a</sub> =85°C	-	1.495	-	V
		VR_LV		T <sub>a</sub> =25℃ R <sub>EXT</sub> =1K	V <sub>DD</sub> =5.5V		1.535	-	V
		VR_HV		IGAIN=100%	V <sub>DD</sub> =2.6V		1.521	-	V
		V <sub>OUT1</sub>		$V_{DD}$ =5.0V	IOUT=18mA	5	350	-	mV
		V <sub>OUT2</sub>		R <sub>EXT</sub> =1k Turning point	IOUT=9mA	-	290	-	mV
Constant flo	w output	V <sub>OUT3</sub>	2	level 0	IOUT=4.5mA	-	260	-	mV
inflection	point	V <sub>OUT4</sub>	2	V <sub>DD</sub> =5.0V R <sub>EXT</sub> =1k Turning point level 1	IOUT=18mA	-	460	-	mV
		V <sub>OUT5</sub>			IOUT=9mA	-	390	-	mV
		V <sub>OUT6</sub>			IOUT=4.5mA	-	360	-	mV
Constant	current	IOUT	2	Turning po	oint level 0	0.5	-	18	mA
source outp	out range	IOUT1	2	Turning po	oint level 1	0.5	-	25	mA
Interchip current	-	DCHIP	2	VDS=	=0.6V		±1.5	± 2.0	%
Interchanne current	•	DCHL	2	VDS=	=0.6V		± 1.2	±2.5	%
Constant error / VI variation a	OS, the	%/Δ VDS	2	VDS=0.	.3~3.0V		_	± 1.0	%/V
Constant error / VDD		%/Δ VDD	2	VDD=3.5V~5.0V		_	_	± 1.0	%/V
Output voltage at the ON		V <sub>O(ON)</sub>	2	OUT0~OUT15		0.3	-	V <sub>DD</sub>	v
SDO drive	high level	IOH	3	3 VDD=5V			-22		mA
current	low level	IOL					23		mA
output level	high level	VOH	4	IOH=	-1mA	4.6	—	—	v

2023/11/14 DP3254\_REV0.3\_EN www.depuw.com

10

德普微电子 DP3254 DP3254 16 Channel 32 scans Low-turning PWM Constant Current Driver

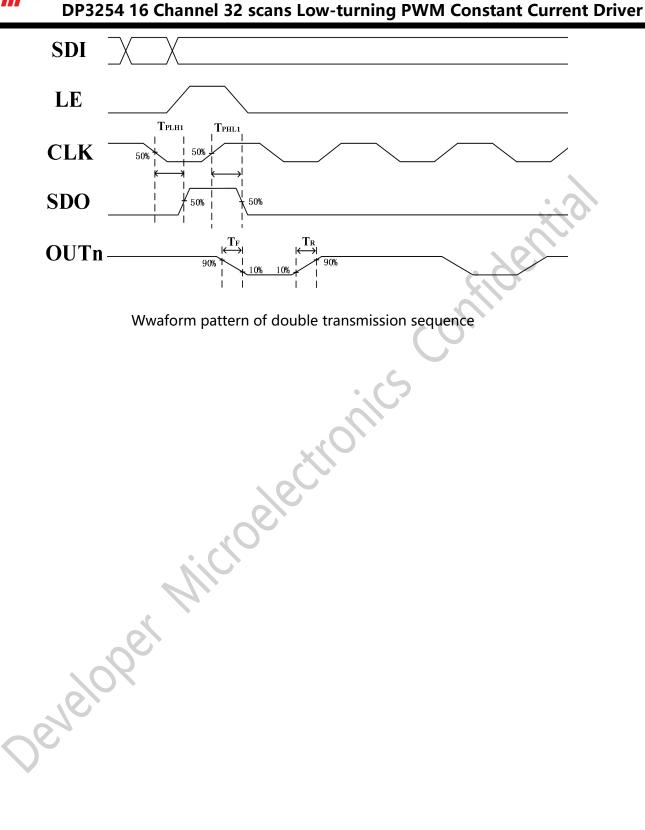
low level	VOL		IOL=1mA			0.4	V
High-level logic input voltage	VUL		-	0.7*V <sub>DD</sub>	_	V <sub>DD</sub>	V
Low-level logic input voltage	V <sub>IL</sub>	5	-	GND	-	0.3*V <sub>DD</sub>	V
Power supply current (with resistance) (White screen power consumption)	I <sub>DD1</sub>	6	R <sub>EXT</sub> =3K, white screen IOUT = 6 mA, with a refresh rate of 3,840	-	4.69	-	mA
	I <sub>DD3</sub>		R <sub>EXT</sub> =3K, black screen IOUT = 6 mA, and the performance is preferred	_	2.95	<u> </u>	mA
Power supply current (with resistance) (Black screen energy- saving power	I <sub>DD4</sub>		R <sub>EXT</sub> =3K, black screen IOUT = 6 mA, and the low power consumption is preferred	O.	1.29	-	mA
consumption)	I <sub>DD5</sub>		R <sub>EXT</sub> =3K, black screen IOUT = 6 mA, with very low power consumption	-	0.68	_	mA
Power supply current (no resistance) (White screen power consumption)	I <sub>DD1</sub>		White screen IOUT = 6 mA, with a refresh rate of 3,840	_	4.26	-	mA
Davies and become	I <sub>DD3</sub>		blank screen IOUT = 6 mA, and the performance is preferred	-	2.88	-	mA
Power supply current (no resistance) (Black screen energy- saving power	I <sub>DD4</sub>	0	blank screen IOUT = 6 mA, and the low power consumption is preferred	-	1.45	_	mA
consumption)	I <sub>DD5</sub>		blank screen IOUT = 6 mA, with very low power consumption	-	0.79	-	mA



## 6.4 Dynamic Characteristics (VDD=3.5V~5V, Ta=25°C)

project	symbol	test circuit	test condition	least value	repres entativ e value	crest value	unit	
The CLK-SDO delay	TPHL			-	15	Ś	ns	
The CLK-SDO delay	TPLH		VDD=5V,	-	15		ns	
The CLK-SDO delay	TPHL 1	7	FDCLK=12.5MHz	Ś	25	-	ns	
The CLK-SDO delay	TPLH 1	,	(	0	15	-	ns	
Constant current output rise time	TR		IOUT=10mA,	-	65	-	ns	
Constant current output drop time	ΤF		ΔVOUT=3V	-	50	-	ns	
SDI XX								
$CLK \xrightarrow{TPLH} \xrightarrow{TPHL} \\ 50\% \xrightarrow{50\%} $								
$OUTn \xrightarrow{T_F} T_R \xrightarrow{T_R} 190\%$								
Time-series waveform diagram of single along transmission sequence								

德普微电子

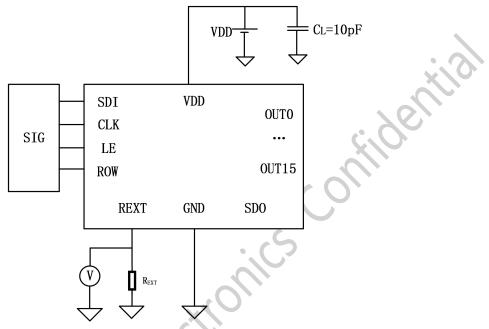


德音微电子 DP3254 DP3254 16 Channel 32 scans Low-turning PWM Constant Current Driver

## 7 Test Circuit Diagrams

## 7.1 Test Circuit 1

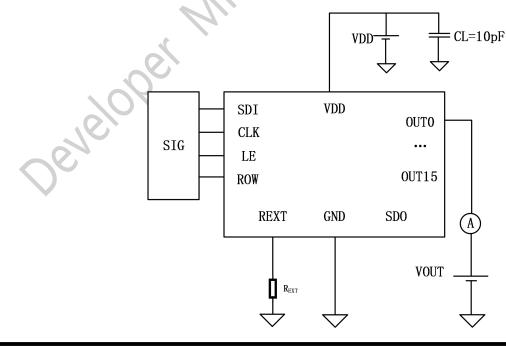
• External resistance voltage



A Schematic diagram of the test circuit 1

## 7.2 Test Circuit 2

• Constant current output inflection point voltage & corresponding inflection point current (in open circuit detection state)



2023/11/14 DP3254 REV0.3 EN www.depuw.com



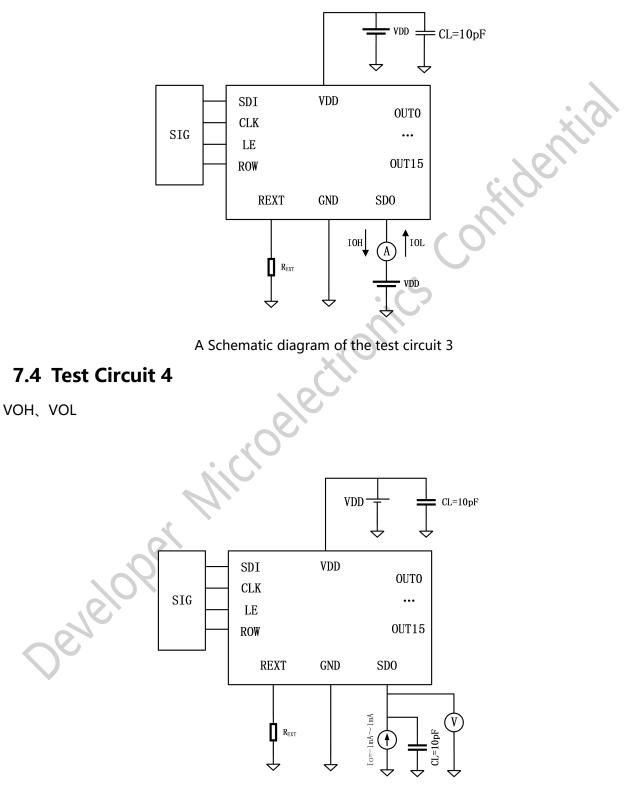
A Schematic diagram of the test circuit 2

Developer Microelectronics Confidential

德普微电子 DP3254 DP3254 16 Channel 32 scans Low-turning PWM Constant Current Driver

#### 7.3 Test Circuit 3

• IOH、IOL



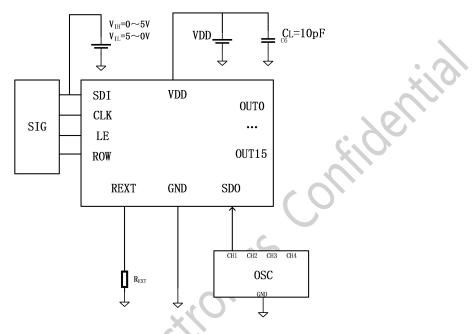
A Schematic diagram of the test circuit 4

www.depuw.com

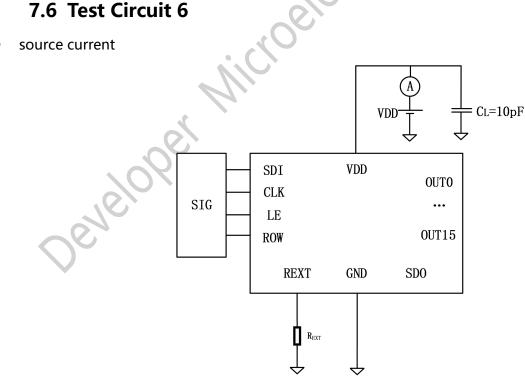


#### 7.5 Test Circuit 5

• VIH、VIL



A Schematic diagram of the test circuit 5



A Schematic diagram of the test circuit 6

www.depuw.com

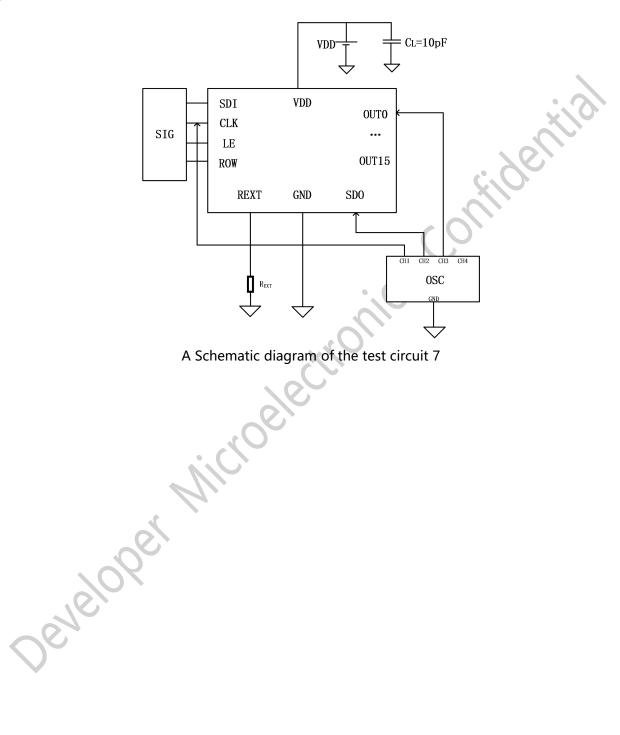
DP3254 16 Channel 32 scans Low-turning PWM Constant Current Driver

**DP3254** 

### 7.7 Test Circuit 7

德普微电子

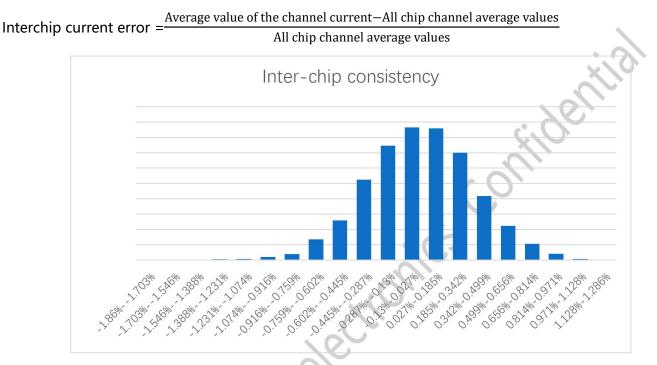
#### • dynamic characteristis



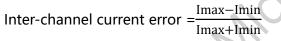
# 8 Typical Feature Diagram

## 8.1 Constant Current Source Accuracy Test Chart

## 8.1.1 Inter-chip Current Error



# 8.1.2 Inter-channel Current Error



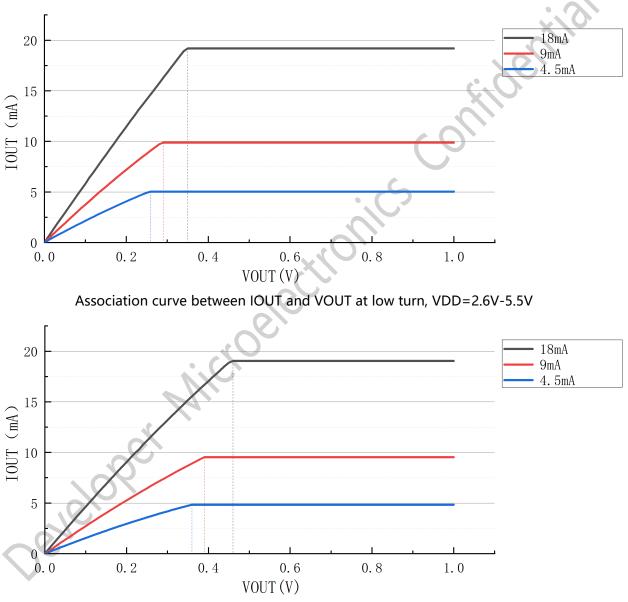


2023/11/14 DP3254 REV0.3 EN www.depuw.com

### 8.2 Constant Flow Source linflection Point

When applying DP3254 to LED display design, the current difference between channels and even between chips is minimal. This is derived from the excellent constant current output characteristics of the DP3254:

- The maximum current between the chip channels is less than ± 2.5%, while the maximum current error between the chips is less than  $\pm$  2.0%;
- When the load end voltage (V out) changes, the stability of the output current is not affected, as shown in the figure below:



The relationship curve between IOUT and VOUT at not low turn, VDD=2.6V-5.5V

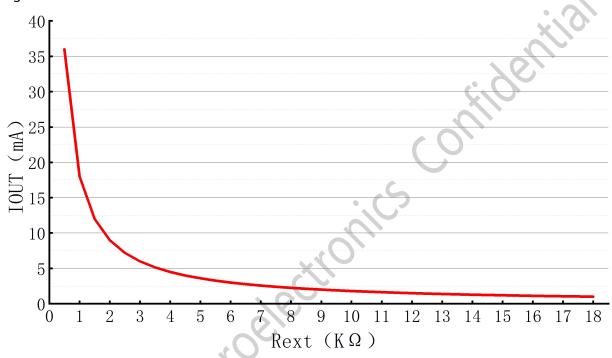


#### 8.3 Adjust The Output Current By Using The External Resistance

The output current value is calculated as follows:

IOUT =  $\frac{IGAIN*18}{Rext} \leq$ , 20% IGAIN 200%  $\leq$ 

R in formula<sub>EXT</sub>Is the ground-to-ground resistance value of the 23PIN REXT port of the chip. For example, when the current gain IGAIN = 100%,  $R_{EXT}At = 1 k\Omega$ , the output current value of 18 mA can be obtained by calculating the formula.



IGAIN=100%, R<sub>EXT</sub>The relationship curve with lout

### 8.4 The No-resistance Mode Adjusts The Current By A Register

The output current value is calculated as follows:

www.depuw.com

The content of the document is a trade secret, without permission, any organization or individual shall not copy and spread in any form!

德普微电子 DP3254 DP3254 16 Channel 32 scans Low-turning PWM Constant Current Driver

## 9 Typical Display Effect Pattern

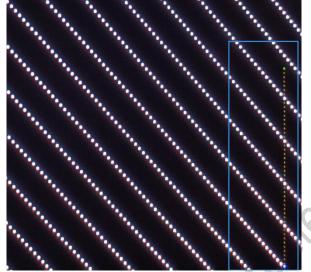
• The specific display effect will be affected by the lamp plate conditions and register parameters, and the following test results are only of reference significance.

## 9.1 Display Effect

## 9.1.1 Remove The Open Circuit Break Point Cross

The following is a comparison of the display effect before and after removing the open circuit broken cross. You can see:

• The chip performs the function of removing the open bad point cross, which can remove the bad point cross and optimize the display effect.



Show the effect before removing the open break point cross



Show the effect after removing the open break point cross

21

# 9.1.2 High and Low Gray Interference and Coupling Display Bad Effect

# Optimization

2023/11/14

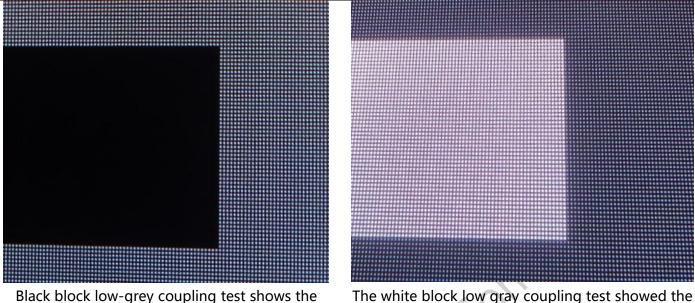
The following figure shows the optimization effect of high and low gray interference and coupling display. It can be seen that:

- Neither the low gray coupling between black block and white block can be felt.
- The chip showed a good display effect.

www.depuw.com



DP3254 16 Channel 32 scans Low-turning PWM Constant Current Driver



effect

The white block low gray coupling test showed the effect

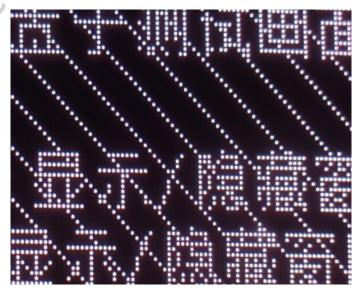
### 9.1.3 Remove Ghostiness and Bandless Lighting Effects

Below is the removal of ghosting and bandless lighting effect that can be seen:

- Inclined scanning under the ghost, text ghost and other problems can not be observed.
- Highlight block with bright, oblique scan superimposed highlight block with bright test shows very good results.
- The chip showed a good display effect



The oblique sweep ghost test showed the effect

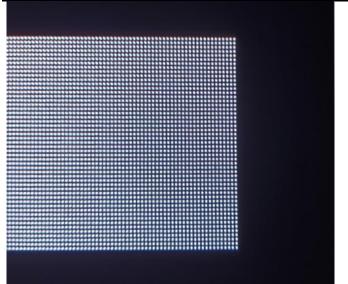


Text ghost test shows the effect



#### **DP3254**

DP3254 16 Channel 32 scans Low-turning PWM Constant Current Driver



德普微电子

The highlight block with the highlight test shows The oblique the effect the effect of the oblique the oblique the oblique the effect of the oblique the effect of the oblique the oblique the oblique the oblique the oblique the effect of the oblique the



The oblique scan stack highlight block highlight test to show the effect

2023/11/14 www.depuw.com 23 DP3254\_REV0.3\_EN The content of the document is a trade secret, without permission, any organization or individual shall not copy and spread in any form! **一 德普微电子** DP3254 DP3254 16 Channel 32 scans Low-turning PWM Constant Current Driver

## **10 Directive and Register**

#### **10.1 Register Instructions**

#### 10.2 Data Command

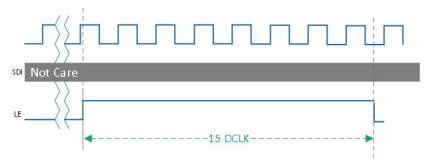
The order of data sent	Line	channel
1	Line 0	Channel 15 (OUT15)
2		Channel 14 (OUT14)
	Ċ	
16	NC.	Channel 0 (OUT0)
17	Line 1	Channel 15 (OUT15)
18		Channel 14 (OUT14)
32		Channel 0 (OUT0)
497	Line 31	Channel 15 (OUT15)
498		Channel 14 (OUT14)
512		Channel 0 (OUT0)
) <b></b>		

# 10.3 Single/Double Mode Switch

- 1. SDI data were sampled along the CLK ascending edge in the single mode, and SDI data were sampled along both CLK ascending edge and descending edge in the double mode.
- 2. The OE signal width was fixed with the CLK ascending edge count
- 3. The odd and double edge mode switch instruction needs to be sent once after the power-on.
- 4. If you need to power up into the single edge mode, you need to send the instructions shown in the

	2023/11/14	www.depuw.com	24
	DP3254_REV0.3_EN		
The content of the document is a trade secret, without permission, any organization or individual shall no			ot
	сору	and spread in any form!	

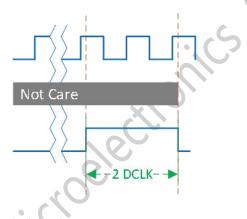
figure below



The 15 DCLK edges (rise + down) are set to SDR

If you need to power up and enter the double edge mode, you need to send the instructions shown

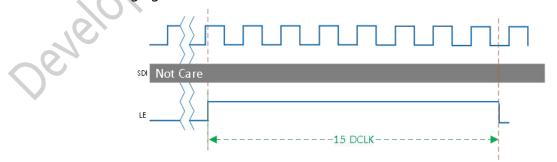
in the figure below



The 2 DCLK ascending edges were set to the DDR

1. If the customer needs to adjust the odd and even edge during the debugging process

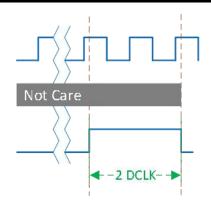
If you are already in the double edge mode and you need to enter the single edge mode, send the instructions in the following figure



The 15 DCLK edges (up + down) are set to SDR

If you are already in the single edge mode, you need to enter the double edge mode

DP3254 DP3254 16 Channel 32 scans Low-turning PWM Constant Current Driver



2 DCLK ascending edges in single edge mode were set to DDR

#### 10.4 Write Register

PRE ACT is sent first, then WR CFG is executed. LE is the width of 5 DCLK, the 8bit is the register address bit, and then the 8bit is the data bit of the corresponding register address.

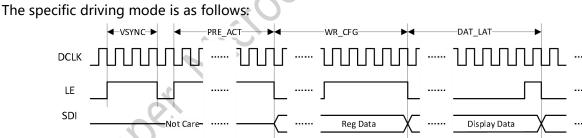
for instance:

{A7, A6, A5, A4, A3, A2, A1, A0} = 8' b0000 0111;

{D7, D6, D5, D4, D3, D2, D1, D0}=8' b1001 1101;

That is, the register 0x07 (8 'b0000 0111) is set to 8' b1001 1101.

## 10.5 Sending Mode of the Register Signal



As shown in the figure above, the order of instructions and data in each frame:

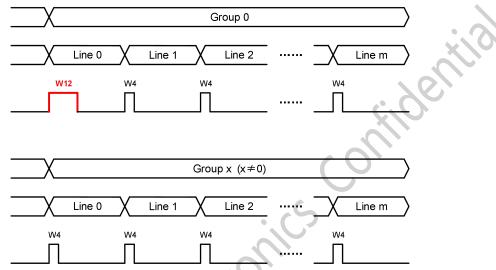
- 1. transmit by radio VSYNC.
- 2. Send the PRE ACT.
- 3. Send the WR CFG, and write to the register configuration. Each frame can write a register value of only one address, and 15 frames can refresh all registers (a total of 15 valid register addresses) to save configuration time.
- 4. Send DAT LAT several times and write the display data with SDI.
- 5. The number of data sent is 16 bits.

#### **10.6 The ROW Signal Transmission Mode**

DP3254 The integrated GCLK generation circuit changes the OE signal of the universal constant current chip to ROW signal and uses ROW

The rising edge of represents the beginning of a row, where there are two types of ROW:

- 1. W12: The high level width representing ROW is the width of 12 DCLK
- 2. W4: The high level width representing ROW is the width of 4 DCLK



As shown in the figure above, when sending ROW signals, only the line 1 (Line 0) of group 1 (Group 0) needs to send W12 ROW signal, and other ROW signals are sent according to W4.

DP3254 16 Channel 32 scans Low-turning PWM Constant Current Driver

#### 10.7 The PWM Display Mode

德晋微电子

DP 3254 Four PWM display modes are integrated in the tablet:

- 1. General frame synchronization mode; 2. Independent refresh synchronization mode of high gray data;
- 3. High gray data independently refresh the asynchronous mode; 4. Low gray and high brush mode

1.Universal frame synchronization mode	
Group 0 X Group 1 X Group 2 X	Group 0
The number of display groups is automatically configured for the control ca Number of groups (rounded) = frame period/display time of a group Display time of a group = display time of a row * number of rows scanned One Line display time = ((2*reg0x05 [7:4] + 2*(reg0x05 [3:0] +1) +4*(reg0	Not display. Wait for V31 NC
	2
2. High gray independent refresh synchronization r	node
Group 0 X Group 1 X Group 2 X	Group n Croup 0 Group 1
The number of display groups is automatically configured for the control of Number of groups (rounded) = frame period/display time of a group Display time of a group = display time of a row * number of rows scanned One Line display time =((2*reg0×05[7:4]+ 2*(reg0×05[3:0]+1)+4*(reg0×04[	
VA ' V	
3. High gray independent refresh asynchronous m	ode
Group 0 X Group 1 X Group 2 X	Group n-2 Group n-1 Group n Group 0
The number of groups displayed is manually configured (the default is 64 g Display time of a group = display time of a row * number of rows scanned	groups)
One Line display time =((2*reg0x05[7:4] + 2*(reg0x05[3:0] + 1) + 4*(reg0x04	4 [6:0] +1))/ (reg0x06 [2:0]) +break time⊢
VA V	
4、Low Ash Hight Brush Mode⇔	
	VSYNC
Group 0 Group 1 Group n Group 0 Group 1	Group 0
	Not Display wait for VSYNCH
One Line display time = ((2*reg0x05[7:4] + 2*(reg0x05[3:0] + 1) + 4*(reg0 Display time of one group=display one line time * numbers of scan# The numbers of group manually configured (default value is 64)#	0x04[6: 0] +1))/ (reg0x06[2:0]) +break time⇔
Hight brush rata (int)= frame period/all groups display time Between adjacent VSYNC it need send rows number = high brush rate +gr	roup+ scans (In the illustration the high brush rate is 2 $\leftrightarrow$

www.depuw.com

**DP3254** 



#### **General Frame Synchronization Mode** 10.7.1

Working mode and related configuration are:

- 1. Configure reg0x0c [7:6] = 0 and set PWM display mode to universal frame synchronization mode
- 2. The number of DCLK in each line is calculated according to Eq.
- 3. Configure the number of data groups, reg0x03 [6:0] = refresh rate / frame rate-1 (maximum of 128 sets of data supported, exceed 128 cluster register)
- 3. Line 1 (Line 0) of Group 1 (Group 0) is displayed after the VSYNC

4. Data display for the current frame is stopped until the arrival of the next VSYNC

#### **Synchronization** 10.7.2 Model High Gray Refresh Frame Data

### Independently

Working mode and related configuration are:

- 1. Configure reg0x0c [7:6] =2, and set the PWM display mode to refresh the frame synchronization mode of the high gray data independently
- 2. Calculate a set of display time = frame period / (refresh rate / frame frequency)
- 3. Calculate the display time of a row = a set of display time / number of rows
- 4. The number of DCLK in each line is calculated according to the formula, which is satisfied by adjusting the series of gray scale and DCLK frequency and register reg0x6 [1:0]
- 5. ROW is sent continuously at a fixed display frequency. The frequency of ROW was not associated with VSYNC

Frequency of the ROW signal = 1 / row of display time = 1 / time between two ROW rise edges 6. Group 0, line 0, sends the ROW signal of W12, and sends the W4 ROW signal in other cases Each ROW signal (group \* row scans) has only one W12 and cycles in this manner.

#### 10.7.3 High-gray data Independently Refreshes Asynchronous Mode

Working mode and related configuration are:

- 1. Configure reg0x0c [7:6] = 3, and set the PWM display mode to refresh the asynchronous mode of the high gray data independently
- 2. The number of DCLK in each line is calculated according to Eq.
- The number of displayed data groups was manually configured, by default to 64 groups (reg0x03 [6:0] =7'h3f).
- 3. ROW is sent continuously according to fixed display frequency. The frequency of ROW was not associated with VSYNC

Frequency of the ROW signal = 1 / row of display time = 1 / time between two ROW rise edges 4. Group 0 row 0 sends ROW signal W12, and otherwise sends ROW signal W4 signal

- Each ROW signal (group (per register configuration) \* row scan) has only one W12 and cycles in this manner. The number of times you can cycle in a frame is unlimited
- 5. Visual refresh rate =1 / (display time \* sweeps of a row)

#### 10.7.4 Low-grey and High-brush Mode

Working mode and related configuration are:

1. Configure reg0x0c [7:6] = 1 and set PWM display mode to low gray high brush mode

2023/11/14

DP3254\_REV0.3\_EN

#### www.depuw.com

**習 微 电 子** 

DP3254

DP3254 16 Channel 32 scans Low-turning PWM Constant Current Driver

- 2. The number of display groups is manually configured (the default configuration is 64 groups)
- 3. The number of DCLK in each line is calculated according to the formula, and the display time of one row is calculated
- 4. Calculate a set of display time = one row display time \* number of rows
- 5. Calculate all groups display time = one group display time \* number of groups,
- 6. High brush rate (consolidation) = frame period / display time of all groups
- 7. Two Vsync before you need to send a high brush rate \* display number of groups \* scan several ROW signals
- 8. Line 1 (Line 0) of Group 1 (Group 0) is displayed after the VSYNC
- 9. The data of the current frame shows high brush times and stops the display until the next VSYNC arrives
- 10. Visual refresh rate = frame rate \* number of data groups \* high brush rate = (3840 / 7680Hz) \* high brush rate
- 11. The low gray and high brush mode only needs to change the ROW signal according to the above steps, and the gray level does not need to be adjusted

## **10.8 Relevant Configuration of PWM Display**

## 10.8.1 Row Scan Number Configuration

DP3254 Maximum support of 32 row sweeps, configured as reg0x02 [5:0] = number of row scans-1

## 10.8.2 Line gray-scale Series Configuration

reg0x04 [6:0] represents the PWM display length of a row, the PWM display length of a row = 4 \* (reg0x04 [6:0] + 1) with maximum support of 64X4=256

For example, if the configuration line gray scale level is 128, then set reg0x04 [6:0] =7'h1f=31

## 10.8.3 PWM Display Packet Configuration

reg0x03 [6:0] shows groups for PWM, and PWM = reg0x03 [6:0] + 1, and the maximum number of supported groups is 128 groups

In frame synchronization mode, PWM displays packet number = refresh rate / frame rate, configuration reg0x03 [6:0] = refresh rate / frame rate-1

In asynchronous mode, PWM display groups can be configured independently (regardless of refresh rate)

## 10.8.4 Internal Grayscale Clock Configuration



DP3254 Integrated PLL produces the gray scale clock GCLK, and the relevant calculation formula is as follows:

```
FGCLK=FDCLK*(reg0x06[2:0]+1)
```

www.depuw.com



#### 10.8.5 PWM Gray Series & Gamma Generation

PWM gray scale (maximum) \* PWM display group =4 \* (reg0x04 [6:0] + 1) \* (reg0x03 [6:0] + 1) -1 for example:

reg0x04[6:0]=7' h7f, reg0x03[6:0]=7' h7f

PWM gray series (maximum) =4 \* (127 + 1) \* (127 + 1) -1=65535=16bit

Gamma can be calculated and generated according to the PWM gray scale series (maximum value) (this part is generated by the control card manufacturer according to its own gamma generation formula)

Up to 16bit only (low 16-bit valid)

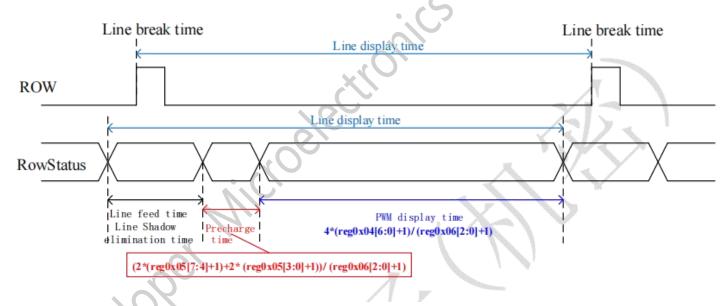
#### **10.8.6** Calculated the Display Time for Each Row

The display time of each row is represented by the number of DCLK, using the calculation formula:

(2 \* (reg0x05 [7:4] + 1) + 2 \* (reg0x05 [3:0] + 1) + 1 \* + 4 \* (reg0x04 [6:0] + 1)) / (reg0x06 [2:0] + 1) + 1 \* change time

Line change time

Note: The results of the above formula are rounded up



# **10.9 Open Circuit Detection and Removal of Bad Spots**

Check [remove bad points]: reg0x0c[1] =1;

Do not check [remove bad points]: reg0x0c[1] =0

Open-circuit detection timing:

2023/11/14

- 1. Perform open circuit detection after 3 seconds or click open circuit detection.
- 2. Configure reg0x02[7] =1, reg0x03[7] =0 (enable open circuit detection mode)

Configuration reg0x0b [7:5] =0 (Configure constant current inflection point to the lowest)

Configure reg0x08 [7:0] right move two bits, high fill 0 (configured output current is 25% of normal

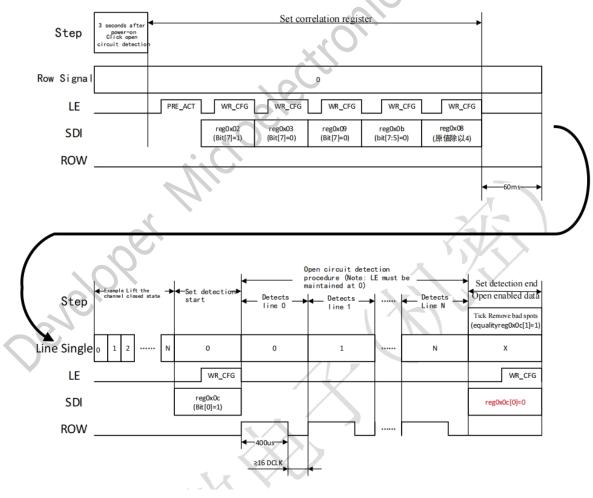
31

DP3254\_REV0.3\_EN The content of the document is a trade secret, without permission, any organization or individual shall not copy and spread in any form!

www.depuw.com

#### current)

- 3. Change to line 0 and stop all row signals for one frame (60ms)
- 4. Change the line signal, quickly scan from line 0 to the last line, and then return to line 0 (this step is mainly to avoid the output channel of the driver chip).
- 5. Configure reg0x0c[0] =1 (open open circuit detection mode)
- 6. Send Row signal, that is, set ow to high, then ROW to low, high level time (400us recommended) as the time required to detect a row, and low level time (16 DCLK recommended) as the data acquisition and latching time.
- 7. Change lines by scanning as many lines as step 6 does. The change time recommended alignment with the rising edge of the ROW.
- 8. After detection, configure reg0x0c[0] =0 (close open circuit detection mode), reg0x0c[1] =1 (when checked [remove bad point]).
- 9. During open circuit detection, LE=0, DCLK is normally sent continuously (at least 128 DCLKs are guaranteed between two ROWs).



www.depuw.com

德普微电子

**DP3254** DP3254 16 Channel 32 scans Low-turning PWM Constant Current Driver

#### 10.10 Register

register	Register function name	Register function description and default values	
0x02		R: 2A G: 2A B: 2A	
7	OPDET_EN_A1	OPDET _ EN _ A 1 is highly efficient; it must cooperate with OPDET _ EN _ A 2, OPDET _ EN _ A 3	
6		Reserved	
5:0	LINE_SET<5:0>	Scan lines = LINE _ SET + 1	
0x03		R: 3F G: 3F B: 3F	
7	OPDET_EN_A2	OPDET _ EN _ A 2 is low effective; cooperate with OPDET _ EN _ A 1, OPDET _ EN _ A 3	
6:0	GROUP_SET<6:0>	Show the refresh rate = REG 03 <6:0> + 1	
0x04		R: 20 G: 20 B: 20	
7		Reserved	
6:0	PWM_WIDTH<6:0>	Number of row GCLK	
0x05		R: 34 G: 34 B: 34	
7:3	DISSHD_TIME_1<3:0>	Shadow time-level 0 ~15 levels, a total of 16 levels, the default value is 0	
2:0	DISSHD_TIME_2<3:0>	Muuation time-0 ~15, a total of 16	
0x06		R: 42 G: 42 B: 42	
7:3	DECOUP_RAT<4:0>	Coupling optimization coefficient	
2:0	PLL_DIV<2:0>	GCLK frequency doubling 0:1 Times frequency 1:2 Times frequency 2:3 Times frequency 3:4 Times frequency	
0x07		R: 00 G: 00 B: 00	
7	Gamma COARSE EN	Gamma coarse tuning switch-1: on 0: off	
6:4	Gamma COARSE<2:0>	Gamma-0-7, a total of 8	
3	Gamma FINE EN	Gamma fine switch-1: fine on 0: fine off	
2:0	Gamma_FINE<2:0>	Gamma fine tuning level-0~7 level, a total of 8 levels	
0x08		R: 7F G: 7F B: 7F	
7:0	IGAIN<7:0>	The reg 08 [7:6] is the 50% progressive bit of the current gain reg08[5:0]= round (128*IGAIN/(reg08[7:6]+1))-1	
0x09		R: 60 G: 60 B: 60	
7	EN_IR	0: Resistance; 1: no resistance	
6:5		Reserved	
4:0	DECOUP_1<4:0>	Coupled optimization level 1-0 to 31, a total of 32 levels	
0x0a		R: BE G: BE B: BE	
7:6	DECOUP_ENHANCE<1:0>	Coupled optimization enhancement rank – successively weakened from 0 to 3	
5		Reserved	
4	DISSHD_EN	Muuation rating switch-on: 1 off: 0	

2023/11/14 DP3254\_REV0.3\_EN www.depuw.com

33



DP3254

DP3254 16 Channel 32 scans Low-turning PWM Constant Current Driver

3	DECOUP_EN	Coupling optimization switch	
2:1	PIT_OPT<1:0>	Low gray point optimization-0 ~3, a total of 4 levels, default level 3	
0	LG_ENHANCE	Low gray display effect enhancement switch	
0x0b		R: 28 G: 30 B: 31	
7:5	CORNER <2:0>	Constant current output inflection point level 0: Low turn (0.18 V-0.3 V) corresponds to the current range of 0.5 mA ~ 18 mA 1: The corresponding current range of non-low turn (0.3 V-0.45 V) is 0.5 mA ~ 25 mA	
4:0	DISSHD_LEVEL<4:0>	Shadow level, level 0 ~31 level, a total of 32 levels	
0x0c		R: 90 G: 90 B: 90	
7:6	SYNC_MODE<1:0>	<ul> <li>0: Frame synchronization mode</li> <li>1: Low gray and high brush mode</li> <li>2: High gray data independently refresh the synchronization mode</li> <li>3: High gray data independently refresh the asynchronous mode</li> </ul>	
5:4	LP_MODE<1:0>	Energy saving mode 0: Dynamic energy saving 1: Dynamic energy saving + black screen energy saving mode 1- Performance priority 2: Dynamic energy saving + black screen energy saving mode 2- Low power consumption first 3: Dynamic energy saving + black screen energy saving mode 3- Very low power consumption	
3:2		Reserved	
1	RM OP	Remove the bad point function switch	
0	OPDET_EN	When the conditions OPDET _ EN _ A 1 and OPDET _ EN _ A 2 are met simultaneously, open OPDET _ EN to enter the open circuit detection mode	
0x0d		R: 08 G: 12 B: 18	
7:5		Reserved	
4:0	DECOUP_LEVEL<4:0>	Coupled optimization level, level 0 to 31, a total of 32 levels	
0x0e		R: 00 G: 00 B: 00	
7:6		Reserved	
5	PRECHA_EN	Enable the coupling optimization of 2	
4:0	VS_PRECHA	Coupled optimization level 2-0 to 31, a total of 32 levels	
0x0f		R: 00 G: 00 B: 00	
7		Reserved	
6:0	IGAINL	'No resistance current adjustment range + / -7.5%, step length 0.5%	
0x10		R: 00 G: 00 B: 00	
7:0		Reserved	
0x11		R: 00 G: 00 B: 00	

2023/11/14

DP3254\_REV0.3\_EN

www.depuw.com



DP3254 16 Channel 32 scans Low-turning PWM Constant Current Driver

7	OPEN_EN_B	Enable the coupling optimization of 1
6:0		Reserved
0x12		R: 00 G: 00 B: 00
7:0		Reserved
0x13		R: 00 G: 00 B: 00
7:0		Reserved
0x14		R: 00 G: 00 B: 00
7:0		Reserved
0x15		R: 00 G: 00 B: 00
7:0		Reserved
0x16		R: 00 G: 00 B: 00
7:0		Reserved
0x17		R: 00 G: 00 B: 00
7:0		Reserved

## 11 Encapsulation Cooling power (P<sub>D</sub>)

The maximum heat dissipation power of the package body is determined by the formula  $P_{D(\max)} = \frac{(T_j - T_a)}{R_{th(j-a)}}$ 

When all the 16 channels are opened, the actual power is:

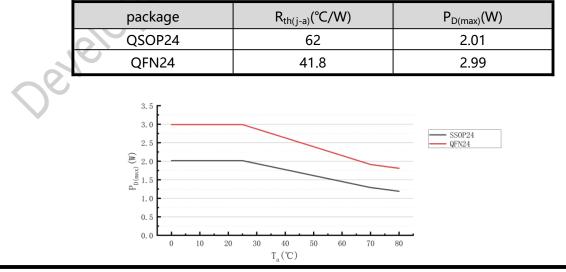
$$P_{D(act)} = I_{DD} * V_{DD} + I_{OUT} * Duty * V_{DS} * 16$$

To ensure that  $P_{D(act)} \leq P_{D(max)}$  The relationship between the maximum current and duty ratio is:

$$I_{OUT (max)} = \frac{\frac{T_{j} - T_{a}}{R_{th(j-a)}} - (I_{DD} * V_{DD})}{V_{DS} * Duty * 16}$$

among  $T_j$ For the junction temperature ( $T_j$ =150°C) ,  $T_a$ For the ambient temperature, and  $V_{DS}$ Is the constant

current output port voltage, Duty is the duty cycle, R<sub>th(j-a)</sub>For the package of the thermal resistance.

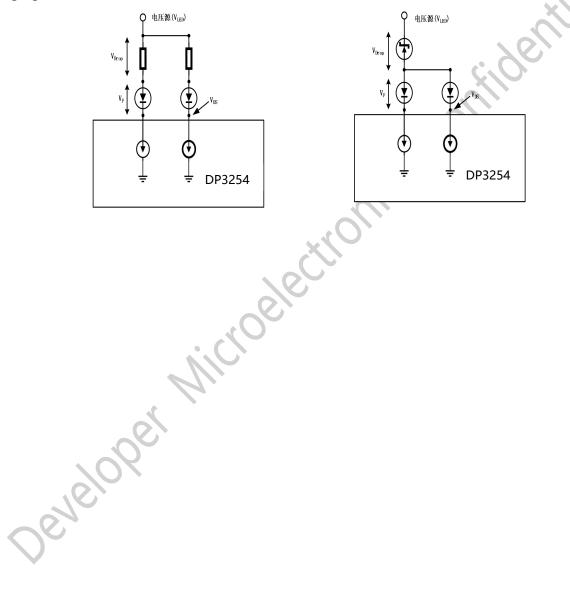


2023/11/14 DP3254 REV0.3 EN www.depuw.com

DP3254

## 12 Load Terminal Voltage (VLED)

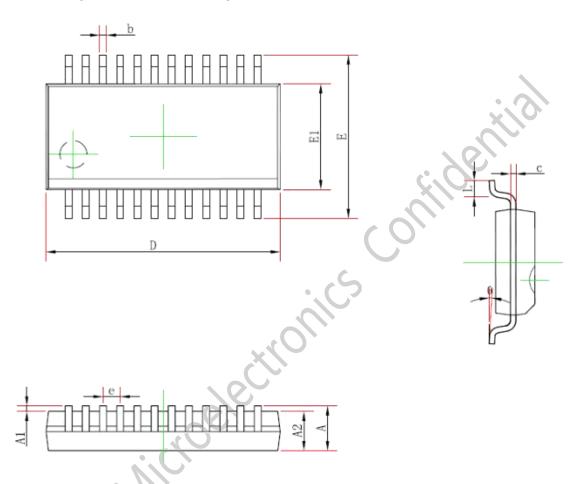
In order to optimize the heat dissipation capacity of the package, the output voltage (V<sub>DS</sub>) The best operating range is  $0.3V \sim 1.0V$  (now  $I_{OUT} = 0.5 \sim 36$  mA). if  $V_{DS} = V_{LED} - V_Fa$  word used in a person's name  $V_{LED} = 5V$ , when too high output voltage ( $V_{DS}$ ) May result cause  $P_{D(act)} > P_{D(max)}$ ; In this case, it is recommended to use a low V as low as possible<sub>LED</sub>Voltage for use, can also be used as an external string resistance or voltage regulator tube as  $V_{DROP}$ . At the moment lead to  $V_{DS} = (V_{LED} - V_F) - V_{DROP}$ , To reduce the input voltage ( $V_{DS}$ ) The effect of the value. The application diagram of the external string resistance or voltage regulator pipe can be referred to in the following figure.



德晋微电子 **DP3254** DP3254 16 Channel 32 scans Low-turning PWM Constant Current Driver

## **13 Encapsulation information**

QSOP24 Plastic sealing specification drawing



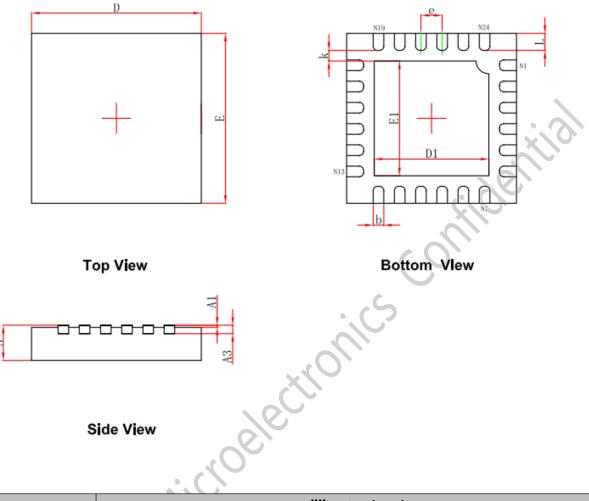
	millimetre (mm)	
	least value (Min)	crest value (Max)
Α		1.95
A1	0.05	0.35
A2	1.05	—
b	0.1	0.4
C	0.05	0.254
D	8.2	9.2
E1	3.6	4.2
E	5.6	6.5
е	0.635TYP	
L	0.3	1.5
θ	0°	10°

DP3254 16 Channel 32 scans Low-turning PWM Constant Current Driver

**DP3254** 

• QFN 24 plastic seal specification drawing

德晋微电子



	millimetre (mm)		
	least value (Min)	crest value (Max)	
Α	0.700/0.800	0.800/0.900	
A1	0.000	0.050	
A3	0.203REF		
D	3.924	4.076	
E	3.924	4.076	
D1	2.6	2.8	
E1	2.6	2.8	
k	0.20MIN		
b	0.200	0.300	
е	0.500TYP		
L	0.324	0.476	



## **14 Official Announcement**

Division I will ensure the accuracy and reliability of the product specification document, but we reserve the right to independently modify the content of the specification document without prior notice to the customer. Before placing an order, customers should contact us to obtain the latest relevant information and verify that this information is complete and up-to-date. All product sales are subject to the sales terms and conditions provided by our company at the time of order confirmation.

Division I will periodically update the content of this document. Actual product parameters may vary due to differences in models or other factors. This document does not serve as any express or implied guarantee or authorization.

The product specification does not include any authorization for the intellectual property owned by our company or any third party. With respect to the information contained in this product specification, we make no explicit or implied warranties, including but not limited to the accuracy of the specification, its fitness for commercial use, suitability for specific purposes, or non-infringement of our company's or any third party's intellectual property. We also do not assume any responsibility for any incidental or consequential losses related to this specification document and its use.

We do not assume any obligations regarding application assistance or customer product design. Customers are responsible for their own use of our company's products and applications. In order to minimize risks associated with customer products and applications, customers should provide thorough design and operational safety validation.

The reproduction, transmission or use of this document or its contents is not permitted without express written authority. Once discovered, the company will pursue its legal responsibility according to law and compensate for all losses caused to the company.

Please note that the product is used within the conditions described in this document, paying particular attention to the absolute maximum rating, operating voltage range, and electrical characteristics. The Company shall not be liable for any damage caused by malfunctions, accidents, etc. caused by the use of the product outside the conditions stated in this document.

Division I has been committed to improving the quality and reliability of products, but all semiconductor products have a certain probability of failure, which may lead to some personal accidents, fire accidents, etc.When designing products, pay full attention to redundancy design and adopt safety indicators, so as to avoid accidents.

When using our chips to produce products, Division I shall not be liable for any patent dispute arising from the use of the chip in the product, the specification of the product, or the country of import, etc., in the event of a patent dispute over the products including the chip.