

DP3252 16 Channel 16 scans Low-turning PWM Constant Current Driver

1 OVERVIEW

DP3252 is a 16-channel low-transition PWM constant-current drive chip designed for LED displays. It integrates high-precision current generation circuit technology on-chip, so that the current error between chips can be controlled within 2.0%, and the new low-gray and high-brush mode is added to improve low-gray refresh rate. And integrated with a number of lifting LED display, the exclusive technology of display effect can bring more improvements.

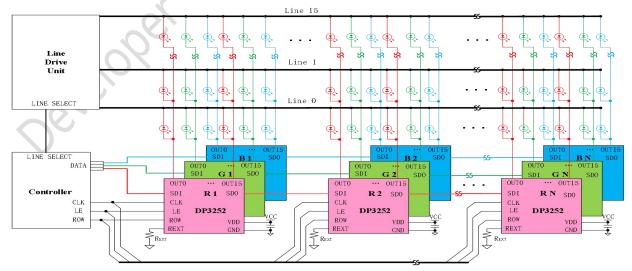
2 FEATURES

- Power supply voltage range: 2.6 ~ 5.5V
- Operating temperature range: -40°C ~ 85°C
- Scanned area : 1 ~ 16 scans , arbitrarily adjustable
- 16 constant current output channels
- Support non-external resistor mode
- Constant current output range
 - $0.5 \text{mA} \sim 18 \text{mA}$ (V_{out}=0.3V)
 - -0.5mA ~ 40mA (V_{out}=0.45V)
- Inter-channel current error
 - Typical value : ± 1.2% Max : ± 2.5% (V_{out}=0.45V)
- Inter-chip current error
 - Typical value: ±1.5% Max: ±2.0%
- High gray independent refresh, no interframe black field
- Low gray high brush, low gray supports 1~8 times display frame rate

- The highest refresh rate supports 128 times frame rate (7680Hz)
- Optimize the display state
 - improve low gray uniformity improve the first line darkening
 - improve up and down ghosting
 - improve high-low gray coupling
 - improve cross-panel coupling
- Integrated PLL produces internal GCLK with lower EMI
- Encapsulation mode: QSOP24/QFN24
- Excellent ESD features

3 APPLICATION FIELDS

- High refresh rate LED video display
- Monochrome two-color or full- color LED display
- High density and small pitch LED panel display



DP3252 Typical Application Schematic

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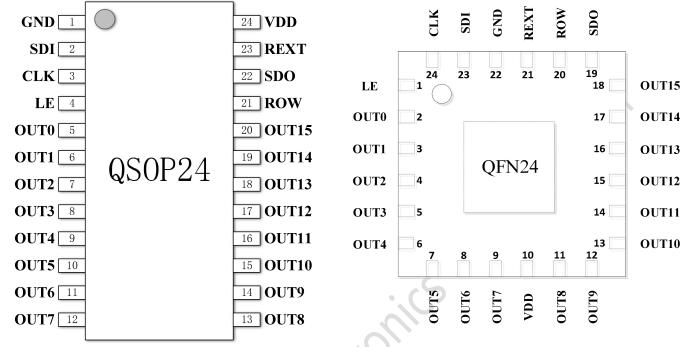
16 Channel PW Constant Current Driver

REVISION RECORD

Version	Date	Reviser	Revised Contents
V0.1	2023.07	Wangmei	Original Version
V0.2	2023.08	Wangmei	Modify instructions and registers

PRODUCTS DESCRIPTION 4

Pin Definition



QSOP24 Pin Definition Diagram

QFN24 Pin Definition Diagram

Pin Description

 Pin Descriptio 	11		
QSOP24 Pin No.	QFN24 Pin NO.	Pin Name	Pin Description
1	22	GND	Chip Grounding Terminal
2	23	SDI	Serial Data Input Terminal
3	24	CLK	Serial Clock Input
4	1	LE	Data and Instruction Latch End, different LE length represents different instructions
5~20	2~9 11~18	OUT0~OUT15	Constant Current Output Terminal
21	20	ROW	Row Switching Signal
22	19	SDO	Serial Data Output
23	21	REXT	Connect the External Resistance Terminal
24	10	VDD	Chip Power Terminal

Product Purchase Information

Product Name	Encapsulation mode	Packing Method	Quantity/Disc	Humidity Level
DDDDDDDDDDDDD	QSOP24	Таре	4000	
DP3252	QFN24	Таре	5000	MSL=3

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Product Marking



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QFN24

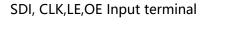
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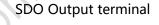
QSOP24

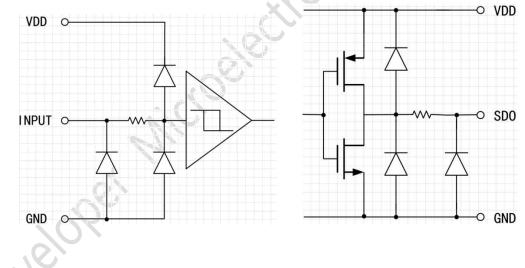
DP3252 is the product name XXXXXX represents th product batch number

5 SCHEMATIC CIRCUIT DIAGRAM

5.1 INPUT/OUTPUT EQUIVALENT CIRCUIT







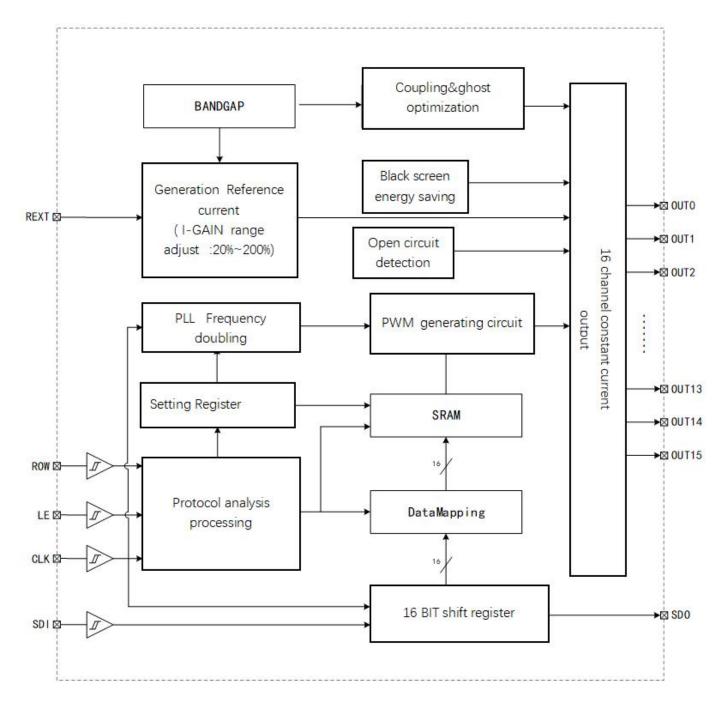
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5.2 INTERNAL CIRCUIT BLOCK DIAGRAM



A Schematic diagram of the internal circuit

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6 PARAMETER LIST

6.1 MAXIMUM LIMIT PARAMETER

Project	Symbol	Rated Value	Unit
Supply Voltage	V _{DD}	0 ~ 5.5	V
Output Current	Ι _ο	40	mA
Input Voltage	V _{IN}	$-0.4 \sim V_{DD} + 0.4$	v
Output withstand voltage	V _{OUT}	11	V
clock frequency	F _{CLK}	25	MHz
Operating Temperature	T _{opr}		-
Storage Temperature	T _{stg}	-55 ~ 150	°C

• All voltage values are based on the chip grounding terminal (GND) as a reference point, and the test temperature for the maximum limit parameter is 25°C.

- If the actual working conditions exceed the specified value may cause permanent damage to the components; If the actual operating conditions are slightly below the maximum and work for a long time, the reliability of the component may be reduced. The above values are only partially specified, and this product does not support functional operation under other conditions outside the specifications.
- The maximum peak welding temperature of surface paste products shall not exceed 260°C. The temperature curve shall be set by the factory according to J-STD-020 standard, the actual situation of the factory and the solder paste manufacturer's suggestion.

6.2 ESD RATING

6.2.1 CONTACT ESD

Symbol	C	Min Value	Typical Value	Max Value	Unit	
	Human-body	OUTn Pin-GND	-	-	-	kV
V	model (HBM) ¹	OTHER Pin-GND	-	-	-	kV
V _(ESD)	Machine Mode	OUTn Pin-GND	-	-	-	kV
	(MM) ²	OTHER Pin-GND	-	-	_	kV

- [1]The minimum HBM model ESD voltage for all pins complies with the Class-3B standard of JEDEC JS-001-2017 document.
- [2] The minimum MM model ESD voltage for all pins complies with the Class-C standard in JEDEC EIA/JESD22-A115C document.

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6.3 ELECTRICAL CHARACTERISTICS (Unless otherwise specified, VDD=3.5V~5V, Ta=25°C)

Project	Symbol	Test Circuit	Test Co	ondition	Mini Value	Typical Value	Max Value	Unit
	VR_TT		V _{DD} =5V,R _{EXT} =1K IGAIN=100%,T _a =25℃		-	1.533	_	v
PEVT voltage	VR_LT		$V_{DD} = 5V$	T _a =-40°C	-	1.56	-	v
REXT voltage characteristics	VR_HT	1	R _{EXT} =1K IGAIN=100%	T _a =85℃	-	1.495	0	V
	VR_LV		$T_a = 25^{\circ}C$	V _{DD} =5.5V	-	1.535	-	V
	VR_HV		R _{EXT} =1K IGAIN=100%	V _{DD} =2.6V	- 0.	1.521	-	V
	V _{OUT1}		V _{DD} =5.0V	IOUT=18mA		350	-	mV
	V _{OUT2}		R _{EXT} =1k	IOUT=9mA	O,	290	-	mV
Constant current output inflection point	V _{OUT3}		拐点等级 0	IOUT=4.5mA	-	260	-	mV
	V _{OUT4}	2	V _{DD} =5.0V	IOUT=18mA	-	460	-	mV
	V _{OUT5}		R _{EXT} =1k 招占等级 1	IOUT=9mA	-	390	-	mV
	V _{OUT6}			IOUT=4.5mA	-	360	-	mV
Constant current	IOUT	2	拐点等	等级 0	0.5	-	18	mA
source output range	IOUT1	2	拐点等	等级 1	0.5	-	40	mA
Inter-chip output current error	DCHIP	2	VDS=	=0.6V		±1.5	± 2.0	%
Output current error between channels	DCHL	2	VDS=	=0.6V	_	± 1.2	±2.5	%
Constant current error/VDS variation	%/ΔVDS	2	VDS=0	.3~3.0V		_	± 1.0	%/V
Constant current error /VDD variation	%/∆VDD	2	VDD=3.	5V~5.0V		_	± 1.0	%/V
output voltage at ON	I V _{O(ON)}	2	OUT0~	OUT15	0.3	-	V _{DD}	V
High SDO drive Level	ЮН	2				-22	_	mA
current Low Level	IOL	3	VDD)=5V		23	_	mA
Output Level	VOH		IOH=	-1mA	4.6	_	_	v
Level Low Level	VOL	4	IOL=	-1mA	_	_	0.4	v
High level logisti	c V _{IH}	5		-	0.7*V _{DD}	-	V _{DD}	V

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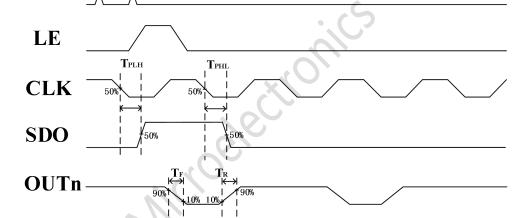
input voltage							
Low level logistic input voltage	V _{IL}		-	GND	-	0.3*V _D	V
Supply current (with resistance) (White screen power consumption)	I _{DD1}	6	R _{EXT} =3K, White Screen IOUT=6mA, Refresh rate 3840	-	4.69	-	mA
Supply current (with	I _{DD3}		R _{EXT} =3K, Black Screen IOUT=6mA, Capability Priority	-	2.95	3	mA
resistance) (Black screen energy- saving power	I _{DD4}	6	R _{EXT} =3K, Black Screen IOUT=6mA, Low power consumption priority	- 2	1.29	-	mA
consumption)	I _{DD5}		R _{EXT} =3K, Black Screen IOUT=6mA, lowest power consumption	9	0.68	-	mA
Power supply current (no resistance) (White screen power consumption)	I _{DD1}		White Screen IOUT=6mA, Refresh Rate 3840	-	4.26	-	mA
Power supply current	I _{DD3}	6	Black Screen IOUT=6mA, Capability Priority	-	2.88	-	mA
(no resistance) (Black screen energy- saving power	I _{DD4}		Black Screen IOUT=6mA, Low power consumption priority	-	1.45	-	mA
consumption)	I _{DD5}	ß	Black Screen IOUT=6mA,lowest power consumption	-	0.79	-	mA
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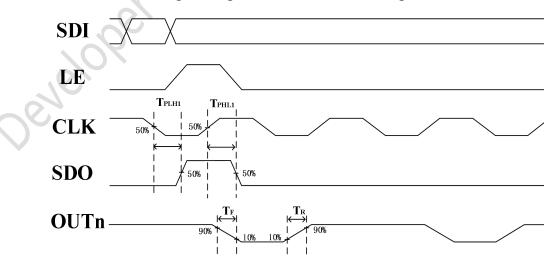
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6.4 DYNAMIC CHARACTERISTICS (Unless otherwise specified, VDD=3.5V~5V, Ta=25°C)

Project	Symbol	Test Circuit	Test Condition	Mini Value	Typical Value	Max Valule	Unit							
CLK-SDO delay	TPHL			-	15	-	ns							
CLK-SDO delay	TPLH		VDD=5V,	-	15	-	ns							
CLK-SDO delay	TPHL1	7	7	FDCLK=12.5MHz	-	25	8	ns						
CLK-SDO delay	TPLH1			7	7	7	7	7	7	7	7		-	15
Constant Current Output Rise Time	TR		IOUT=10mA,	-C	65	-	ns							
Constant current output drop time	TF		ΔVOUT=3V	6	50	-	ns							
SD	SDI XX													



Single along time series waveform diagram



Double along time sequence waveform diagram

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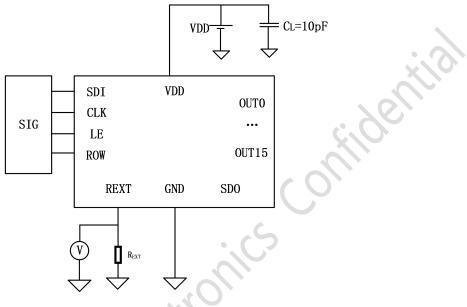
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7 TEST CIRCUIT DIAGRAM

7.1 TEST CIRCUIT 1

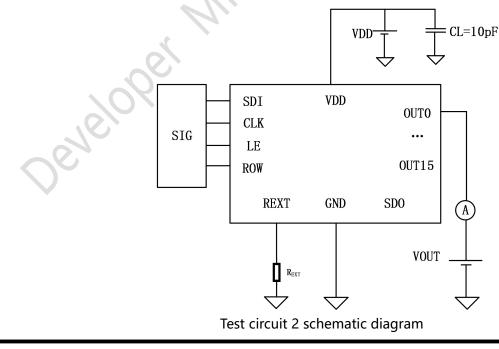
• External resistance voltage



Test circuit 2 schematic diagram

7.2 TEST CIRCUIT 2

• Constant current output inflection point voltage & corresponding inflection point current (under open circuit detection)



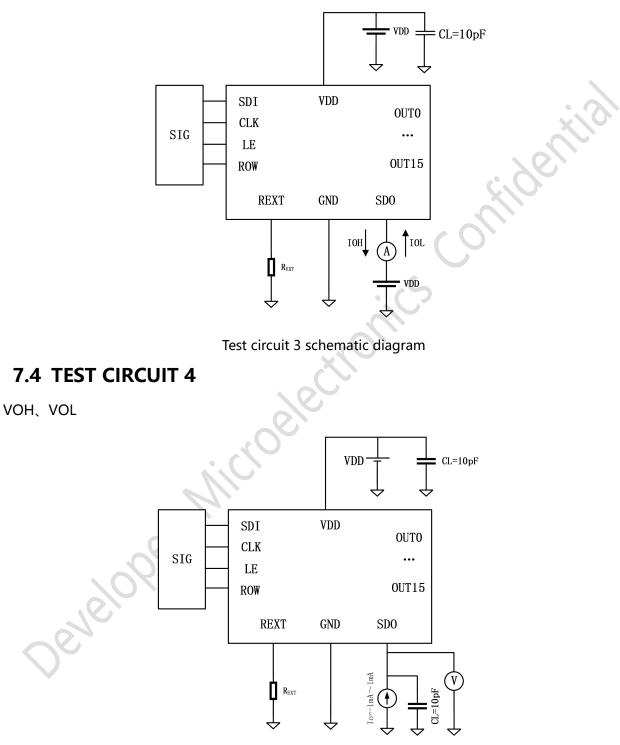
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7.3 TEST CIRCUIT 3

IOH、IOL



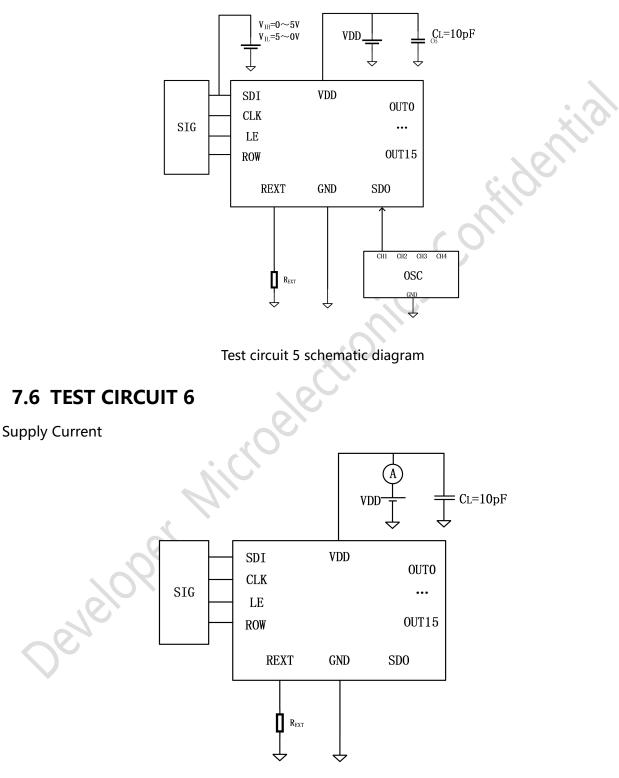
Test circuit 4 schematic diagram

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7.5 TEST CIRCUIT 5

• VIH、VIL



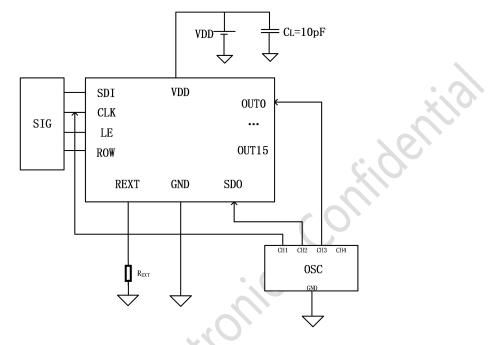
Test circuit 6 schematic diagram

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7.7 TEST CIRCUIT 7

• Dynamic Characteristic



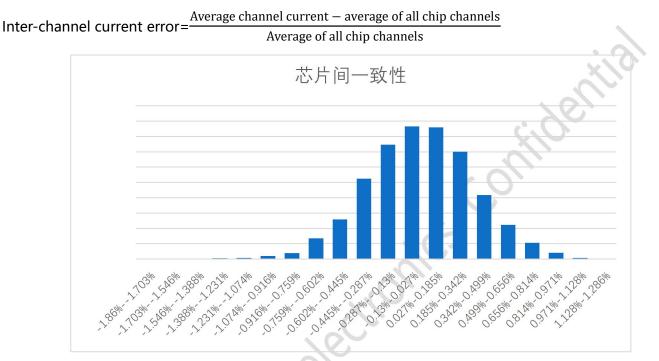
Test circuit 7 schematic diagram

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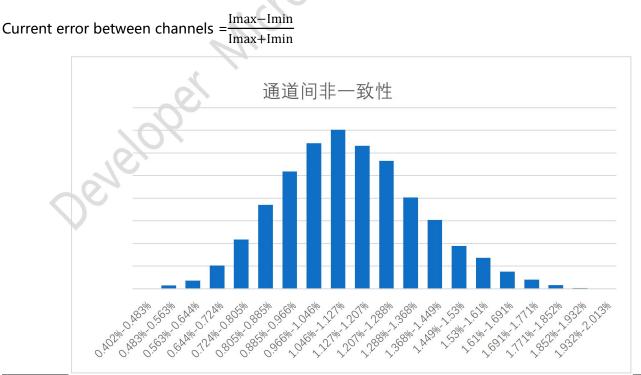
8 TYPICAL CHARACTERISTIC DIAGRAM

8.1 CONSTANT CURRENT SOURCE ACCURACY TEST CHART

8.1.1 INTER-CHIP CURRENT ERROR



8.1.2 INTER- CHANNEL CURRENT ERROR



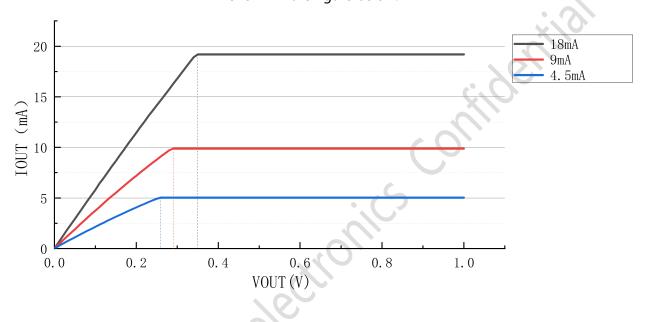
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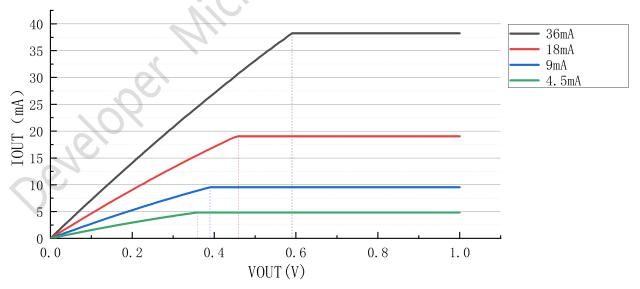
8.2 CONSTANT CURRENT SOURCE INFLEXION POINT

When the DP3252 is applied to the design of LED displays, the current differences between channels and even between chips are minimal. This is due to the DP3252's excellent constant current output characteristics:

- The maximum on-chip channel current is less than ±2.5%, and the maximum on-chip current error is less than ±2.0%;
 - When the load terminal voltage (Vout) changes, the stability of the output current is not affected, as shown in the figure below:



The relationship between IOUT and VOUT when VDD=2.6V-5.5V is low transition



The relationship between IOUT and VOUT when VDD=2.6V-5.5V is not low transition

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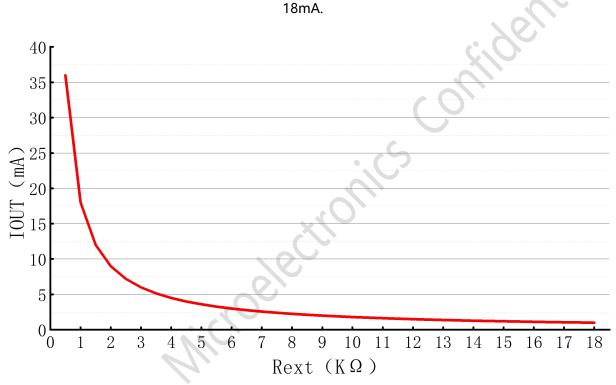
8.3 ADJUST OUTPUT CURRENT BY AN EXTERNAL RESISTOR

Output current value is calculated by the following formula:

$$IOUT = \frac{IGAIN*18}{Rext}, 20\% \le IGAIN \le 200\%$$

The REXT in the formula is the resistance to the ground of the chip's 23PIN REXT port. For example, when the

current gain IGAIN=100%, REXT=1k Ω , the output current value can be obtained by calculating the formula



IGAIN=100%, the relationship between REXT and lout

8.4 RESISTIVE-FREE MODEL WITH CURRENT ADJUSTED BY REGISTER

Output current value is calculated by the following formula:

lout=[70uA+0.4uA*(reg0x0f<6:0>-16)]*reg0x08<7:0>*(1+0.5*reg0x0b<5>)

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9 TYPICAL DISPLAY EFFECT SAMPLE IMAGE

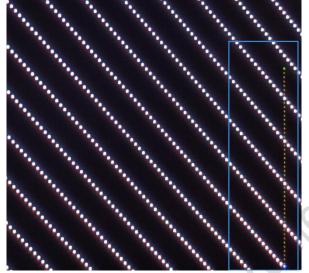
• The specific display effect will be affected by the conditions of the lamp board and register parameters. The following test results are for reference only.

9.1 DISPLAY EFFECT

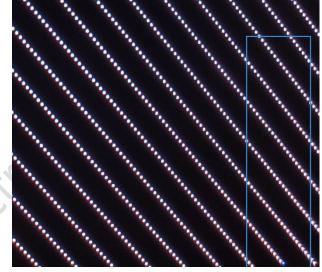
9.1.1 REMOVE OPEN CIRCUIT BAD SPOT CROSSES

The following is a comparison of the display effect before and after removing the open circuit bad spot cross, you can see:

• Chip can remove the bad cross well after removing the open bad cross function, optimize the display effect.



Display Effect before Removing open circuit bad spots cross



Display effect after removing the open circuit bad spot cross

9.1.2 HIGH AND LOW GRAY INTERFERENCE AND COUPLING DISPLAY BAD

EFFECT OPTIMIZATION

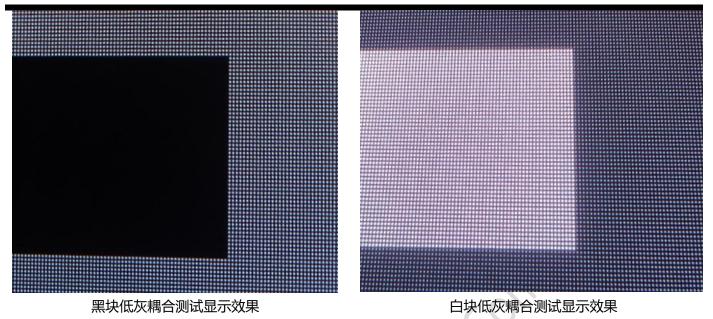
The following figure is the optimization effect of high-low gray interference and coupling display poor effects can be seen:

- The low gray coupling of the block and the low gray coupling of the white block are not sensed.
- Chip show good display effect.

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9.1.3 REMOVE GHOSTINESS AND BANDLESS LIGHTING EFFECTS

Below is the removal of ghosting and bandless lighting effect that can be seen:

- Oblique scanning ghost, text ghost and other problems cannot be observed.
- Highlight block with bright, oblique scan superimposed highlight block with bright test results are very good.
- Chip shows good display effect

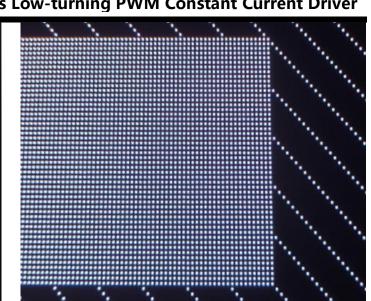
Slanted scan ghosting test display effect



Text ghosting test display effect



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Highlight block with light test display effect

Oblique scan superimposed highlight block with light test display effect

10 INSTRUCTION AND REGISTER

10.1 REGISTER INSTRUCTION

Instruction Name	LE	Description
DATA_LATCH	.1	Latch 16bit data to SRAM
DDR	2	Enter Double-edge Mode
VSYNC	3	Update Display Data
WR_CFG	5	Write Register
PRE_ACT	14	Write Enable
SDR	15	Enter Single-edge Mode
SDR	15	Enter Single-edge Mode

10.2 DATA INSTRUCTIONS

Data sending Sequence	Line	Channel
1	Line 0	Channel 15 (OUT15)
2		Channel 14 (OUT14)
16		Channel 0 (OUT0)

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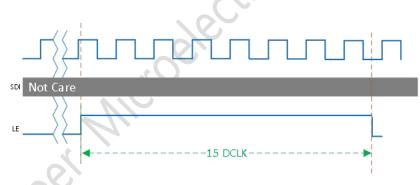
17	Line 1	Channel 15 (OUT15)		
18]	Channel 14 (OUT14)		
32		Channel 0 (OUT0)		
497	Line 15	Channel 15 (OUT15)		
498		Channel 14 (OUT14)		
512		Channel 0 (OUT0)		

10.3 SINGLE/DOUBLE MODE SWITCH

1. Sample SDI data with CLK rising edge in single edge mode, and sample SDI data with CLK rising edge and falling edge in double edge mode.

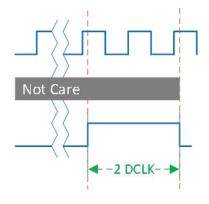
- 2. CLK rising edge counting is used for fixed OE signal width
 - 3. The command for single-mode and dual-mode along mode switchover needs to be sent once after it is powered on

To enter the single-edge mode after power-on, send the command shown in the following figure:



15 DCLK edges (up + down) are set to SDR

To enter the dual-edge mode after power-on, send the command shown in the following figure

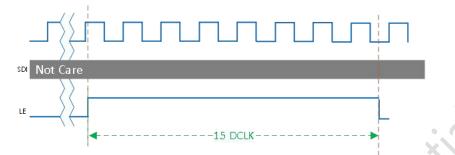


The two DCLK rising edges are set to DDR

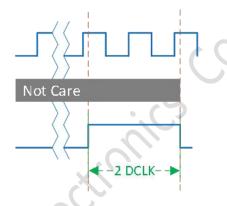
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If the customer needs to adjust the single and double edges during debugging If already in dual edge mode and need to enter single edge mode, send the following command



In double edge mode, 15 DCLK edges (up + down) are set to SDR If already in single edge mode, you need to enter double edge mode



In single-edge mode, the two DCLK rising edges are set to DDR

10.4 WRITE REGISTER

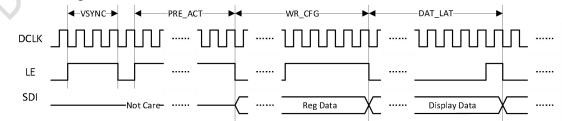
Send PRE_ACT first, then run WR_CFG, LE is 5 DCLK width, the first input 8bit is the register address bit, the last input 8bit is the data bit of the corresponding register address.

For example:

{A7, A6, A5, A4, A3, A2, A1, A0} = 8' b0000_0111; {D7, D6, D5, D4, D3, D2, D1, D0}=8' b1001_1101; That is, register 0x07 (8 'b0000_0111) is set to 8' b1001_1101.

10.5 REGISTER SINGAL SENDING WAY

The specific driving methods are as follows:



As shown in the figure above, the order of sending instructions and data in each frame:

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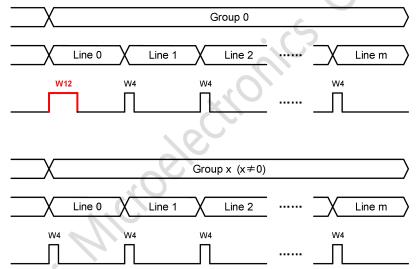
- 1. Send VSYNC。
- 2. Send PRE_ACT。
- 3. Send WR_CFG and write the register configuration. Each frame can only write a register value of one address, and 15 frames complete the refresh of all registers (a total of 15 valid register addresses) to save configuration time.
- 4. Send DAT_LAT several times to write display data together with SDI.
- 5. The data sending bit is displayed as 16 bits.

10.6 ROW SIGNAL SENDING WAY

The DP3252 integrated on-chip GCLK generation circuit changes the OE signal of the universal constant current chip to the ROW signal, using ROW the rising edge of the ROW represents the beginning of a row display, where the high level width of the row has two types, namely:

1.W12: The high-level width of the ROW is 12 DCLK width

2.W4: The high-level width of the ROW is 4 DCLK width



As shown in the figure above, when ROW signals are sent, only the first ROW of Group 1 (Line 0) needs to send ROW signals of W12, and other ROW signals are sent according to W4.

10.7 PWM DISPLAY MODE

DP3252 integrated four PWM display modes:

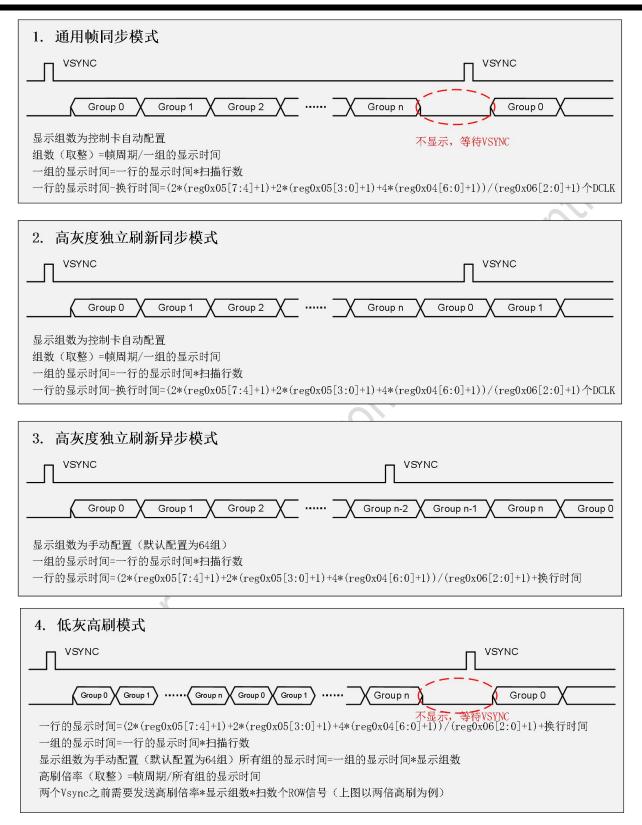
- 1. General frame synchronization mode; 2. High-gray data independent refresh synchronous mode;
- 3. High-gray data independently refreshes asynchronous mode; 4. Low Ash High Brush mode

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10.7.1 GENERAL FRAME SYNCHRONIZATION MODE

Working mode and related configurations as follow:

- 1. Configure REG0X0C [7:6] = 0 and set the PWM display mode to Universal Frame Sync Mode
- 2. The number of DCLK per line is calculated using the Formula
- 3. The configuration shows the number of data sets, REG0X03[6:0] = refresh rate/frame rate -1(if refresh rate is not equal to 3840 or 7680, use Depp's gamma DLL)
- 4. After VSYNC, the first Line (Line 0) of Group 1(Group 0)
- 5. Stop displaying data from the current frame until the next VSYNC comes

10.7.2 HIGH GRAY DATA REFRESH FRAME SYNCHRONIZATION MODEL

INDEPENDENTLY

Working mode and related configurations as follow:

- 11. Configure REG0X0C [7:6] = 2, set PWM display mode to high gray data independent refresh frame synchronization mode under this mode display refresh rate support 3840HZ ~ 7680HZ, configure display data group register reg0x03[6:0] = 127
- 2. Calculate a set of display times = frame period/(refresh rate/frame rate)
- 3. Calculate the display time of a row = a set of display times/number of rows
- 4. The DCLK number of each row is calculated according to the formula, and the formula is satisfied by adjusting the row gray level series, the DCLK frequency and the register reg0x6[1:0].
- 5. Row is sent continuously at a fixed display frequency. The frequency of the ROW is independent of VSYNC the frequency of the ROW signal = 1/1 ROW display time = 1/2 time between the rising edges of the ROW
- 6. Row 0 of group 0 sends the ROW signal of W12, other cases send the ROW signal of W4 every (group number * ROW scan number-RRB- ROW signal, only W12 W12, and in this way has been circulating.
- 7. If the refresh rate is not equal to 3840 or 7680, you need to use Depp's gamma dll

10.7.3 HIGH-GRAY DATA INDEPENDENTLY REFRESHES

ASYNCHRONOUS MODE

Working mode and related configurations as follow:

1. Configure REG0X0C [7:6] = 3, set the PWM display mode to high gray data independent refresh asynchronous mode

2. The number of DCLKS per line is calculated using the Formula

Displays the number of data groups manually configured, the default is 64 groups (reg0x03[6:0] = 7' H3F).

3. ROW continuously transmission at a fixed display frequency without interruption, and ROW frequency is independent of VSYNC.

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Row signal frequency = 1/1 ROW display time = 1/2 ROW rise edge time

4. Row 0 of group 0 sends the ROW signal of W12, other cases send the ROW signal of W4 per (group number (as per register configuration value) * ROW scan number-**RRB**- ROW signal, only W12, and in this way has been circulating. There is no limit to the number of cycles allowed in a frame.

5. Visual refresh rate = 1/(one line display time * scans)

10.7.4 LOW GRAY HIGH BRUCH MODE

Working mode and related configurations as follow:

1. Configure REG0X0C [7:6] = 1, set PWM display mode to Low Ash High Brush Mode

2. Display the number of groups manually (the default is 64) . If the refresh rate is not equal to 3840 or 7680, use Depp's gamma DLL

3. The DCLK number of each row is calculated according to the formula, and the display time of a row is calculated

4. Calculate a set of display times = one line of display times * number of lines

- 5. Calculate all group display times = one group display times * number of groups
- 6. High brush rate (rounded) = frame period/display time for all groups

7. Before both VSYNC need to send a high brush rate * display array number * scan several ROW signals

8. After VSYNC, Line 1(Line 0) of Group 1(Group 0)

9. The data for the current frame is displayed at a high brush rate and then stopped until the next VSYNC arrival.

10. Visual refresh rate = frame rate * data set * high refresh rate = (3840/7680 Hz) * high refresh rate 11. The low-gray high-brush mode only needs to change the ROW signal according to the above steps, the gray level does not need to be adjusted.

10.8 RELEVANT CONFIGURATION OF PWM DISPLAY

10.8.1 NUMBER OF ROW SCANS CONFIGURED

DP3252 supports up to 32 line scans, configured as REG0X02[5:0] = number of line scans -1 **10.8.2**

Reg0x04[6:0] represents a row of PWM display length, one row of PWM display length = 4 * (reg0x04[6:0] + 1), maximum support 128x4 = 512 if the configuration row gray level is 128, then set reg0x04[6:0] = 7' H1F = 31

10.8.3 **PWM DISPLAY PACKET CONFIGURATION**

Reg0x03[6:0] represents the number of PWM groups, PWM shows the number of groups = Reg0x03[6:0] + 1, the maximum number of support groups is 128 groups

In frame synchronous mode, PWM display group number = refresh rate/frame rate, configure reg0x03[6:0] = refresh rate/frame rate -1

In asynchronous mode, the PWM display packet can be configured independently (independent of the refresh rate)

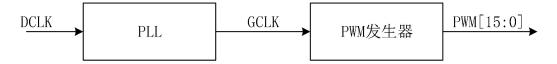
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10.8.4 INTERNAL GRAYSCALE CLOCK CONFIGURATION



DP3252 integrates PLL on chip to produce gray clock GCLK. The relevant calculation formula is as follows: FGCLK=FDCLK*(reg0x06[1:0] +1)

10.8.5 PWM GRAYSCALES SERIES & GAMMA GENERATION

PWM gray-scale series (maximum) = * PWM gray-scale series show grouping = 4 * (reg0x04 [lost] + 1) * (reg0x03 [lost] + 1) - 1

reg0x04[6:0]=7' h7f, reg0x03[6:0]=7' h7f

PWM gray level (maximum)=4*(127+1)*(127+1)-1=65535=16bit

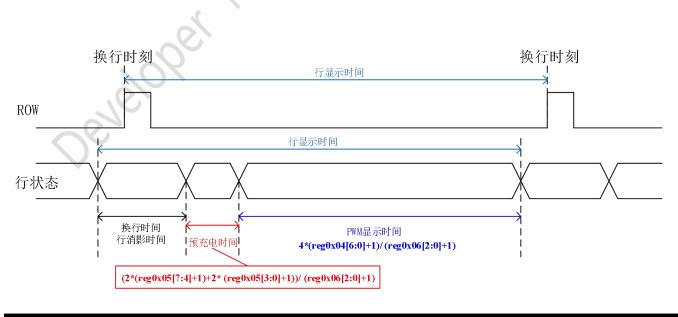
Gamma can be calculated and generated according to the PWM gray level (maximum) (this part is generated by the control card manufacturer according to their own gamma generation formula)

The maximum chip gray level only supports 16bit (low 16 bits are valid).

10.8.6 CALCULATED THE DISPLAY TIME FOR EACH ROW

The display time of each line is expressed by the number of DCLK, and the calculation formula is as follow:

(2*(reg0x05[7:4] +1) +2*(reg0x05[3:0] +1) +4*(reg0x04[6:0] +1))/(reg0x06[2:0] +1) + break time Note: the above results are rounded.



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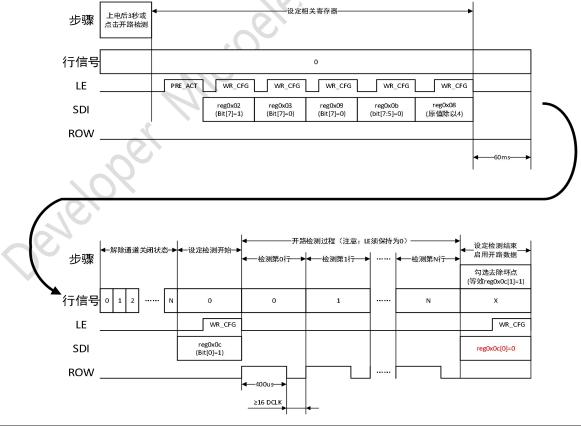
10.9 OPEN CIRCUIT DETECTION AND REMOVAL OF BAD SPOTS

Selected [Remove bad spots] : reg0x0c[1]=1 ;

Non-selected [Remove bad spots] : reg0x0c[1]=0

Open circuit detection timing:

- 1. The open circuit test is performed 3 seconds after power-on or after clicking open circuit test.
- 2. Configure reg0x02[7]=1, reg0x03[7]=0 (Enable Open detection mode)
 Configure reg0x0b[7:5]=0 (Set constant current inflection point to the lowest)
 Configure reg0x08[7:0] move two digits to the right and fill the high position with 0, (configure output current to 25% of normal)
- 3.Line signal switch to line 0 and stop all line signals for one frame time (60ms)
- 4. Change the line signal, quickly scan from line 0 to the last line, and then back to line 0 (this step is mainly to avoid the closure of the output channel that exists in some line driver chips).
- 5. Configure reg0x0c[0]=1 (Open detection mode is enabled)
- 6. Sending a Row signal, set the Row to high first and then to low. The high level time (400us recommended) is the time required for detecting a ROW, and the low level time (≥16 DCLK recommended) is the data collection and latch time.
- 7. Line feed, as many lines as need to be scanned, step 6 perform as many times. Line breaks are recommended to align with the rising edge of the ROW.
- 8. After the detection is complete, configure reg0x0c[0]=0 (Turn off open detection mode), reg0x0c[1]=1 (selected **[Remove bad spots]**).
- 9. During open-circuit detection, LE=0, DCLK is normally transmitted continuously (at least 128 DCLK between two rows are guaranteed).



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10.10 REGISTER

Register	Register Function Name	Register function description & default value	
0x02		R: 2A G: 2A B: 2A	
7	OPDET_EN_A1	OPDET_EN_A1 High effective; It must work with OPDET_EN_A2 and OPDET_EN_A3	
6		Reserved	
5:0	LINE_SET<5:0>	Scanning Lines= LINE_SET +1	
0x03		R: 3F G: 3F B: 3F	
7	OPDET_EN_A2	OPDET_EN_A2 is low valid. It must work with OPDET_EN_A1 and OPDET_EN_A3	
6:0	GROUP_SET<6:0>	Display refresh ratio =REG03<6:0>+1	
0x04		R: 20 G: 20 B: 20	
7		Reserved	
6:0	PWM_WIDTH<6:0>	Row GCLK number	
0x05		R: 34 G: 34 B: 34	
7:3	DISSHD_TIME_1<3:0>	Shadow elimination Time -0 to 15, total16 levels, the default value is 0	
2:0	DISSHD_TIME_2<3:0>	Shadow elimination time -0 ~15, total 16 levels	
0x06		R: 42 G: 42 B: 42	
7:3	DECOUP_RAT<4:0>	Coupling optimization coefficient	
2:0	PLL_DIV<2:0>	 GCLK frequency doubling 0: 1 frequency doubling 1: 2 frequency doubling 2: 3 frequency doubling 3: 4 frequency doubling 	
0x07		R: 00 G: 00 B: 00	
7	Gamma_COARSE_EN	Gamma Coarse switch -1: coarse switch enabled 0: coarse switch off	
6:4	Gamma_COARSE<2:0>	Gamma 粗调等级-0~7级, 共8级	
3	Gamma_FINE_EN	Gamma fine-tune switch -1: fine-tune enabled 0: fine-tune disabled	
2:0	Gamma_FINE<2:0>	Gamma Fine level -0 to 7, 8 in total	
0x08		R: 7F G: 7F B: 7F	
7:0	IGAIN<7:0>	reg08[7:6] is a progression of 50% of the current gain reg08[5:0]= round (128*IGAIN/(reg08[7:6]+1))-1	
0x09		R: 60 G: 60 B: 60	
7	EN_IR	0: resistance 1: non-resistance	
6:5		Reserved	
4:0	DECOUP_1<4:0>	Coupling optimization level 1-0 ~31, total 32 levels	
0x0a		R: BE G: BE B: BE	
7:6	DECOUP_ENHANCE<1:0>	Coupling optimization enhancement level - decreases from 0 to 3	
5		Reserved	

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4	DISSHD EN	Extinction level switch - On :1 Off: 0	
3	 DECOUP_EN	Coupling optimization switch	
2:1	PIT_OPT<1:0>	Low grey pitting optimization -0 ~3, total 4 levels, the default is level 3	
0	LG_ENHANCE	Low gray display effect enhancement switch	
0x0b		R: 28 G: 30 B: 31	
7:5	CORNER <2:0>	Constant current output inflection point level 0: low inflection point (0.18 V - 0.3 V) corresponds to the current range of 0.5mA~18mA 1: Non- low inflection point (0.3 V - 0.45 V) corresponds to the current range of 0.5mA~25mA	
4:0	DISSHD_LEVEL<4:0>	Shadow Elimination level, 0~31 level, total 32 levels	
0x0c		R: 90 G: 90 B: 90	
7:6	SYNC_MODE<1:0>	 0: frame synchronization mode 1: Low gray high brush model 2: High gray data independently refreshed in synchronization model 3: High gray data independently refreshed in asynchronous mode 	
5:4	LP_MODE<1:0>	 Energy-saving model Oynamic energy saving Dynamic Energy saving + Black screen energy saving mode 1- Performance is preferred Dynamic Energy Saving + Black screen Energy Saving mode 2- Low power consumption is preferred Dynamic Energy Saving + Black Screen Energy Saving Mode 3- Extremely low power consumption 	
3:2		Reserved	
1	RM_OP	Remove the bad spot function switch	
0	OPDET_EN	If both OPDET_EN_A1 and OPDET_EN_A2 are met, OPDET_EN is enabled to enter the open detection mode	
0x0d		R: 08 G: 12 B: 18	
7:5		Reserved	
4:0	DECOUP_LEVEL<4:0>	Coupling optimization level, 0 ~31, total 32 levels	
0x0e		R: 00 G: 00 B: 00	
7:6		Reserved	
5	PRECHA_EN	Enable coupling Optimization 2	
4:0	VS_PRECHA	Coupling optimization level 2-0 ~31, total 32 levels	
0x0f		R: 00 G: 00 B: 00	
7		Reserved	
6:0	IGAINL	'Resistance-free current regulation range +/-7.5%, step length 0.5%	
0x10		R: 00 G: 00 B: 00	
7:0		Reserved	

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0x11		R: 00 G: 00 B: 00
7	OPEN_EN_B	Enable coupling optimization 1
6:0		Reserved
0x12		R: 00 G: 00 B: 00
7:0		Reserved
0x13		R: 00 G: 00 B: 00
7:0		Reserved
0x14		R: 00 G: 00 B: 00
7:0		Reserved
0x15		R: 00 G: 00 B: 00
7:0		Reserved
0x16		R: 00 G: 00 B: 00
7:0		Reserved
0x17		R: 00 G: 00 B: 00
7:0		Reserved

11 ENCAPSULATION COOLING POWER (P_D)

The maximum heat dissipation power of the encapsulation is determined by the formula: $P_{D(\max)} = \frac{(T_j - T_a)}{R_{th(j-a)}}$

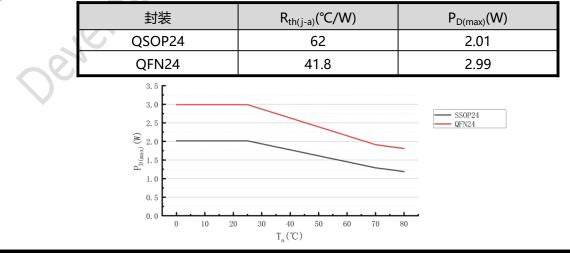
When all 16 channels are open, the actual power is:

$$P_{D(act)} = I_{DD} * V_{DD} + I_{OUT} * Duty * V_{DS} * 16$$

To ensure that $P_{D(act)} \leq P_{D(max)}$ output maximum current and duty cycle relationship is:

$$I_{OUT (max)} = \frac{\frac{T_{j} - T_{a}}{R_{th(j-a)}} - (I_{DD} * V_{DD})}{V_{DS} * Duty * 16}$$

Therein T_j is the junction temperature (T_j =150°C), T_a is the ambient temperature, V_{DS} is the constant current output port voltage, Duty is the duty cycle, and $R_{th(j-a)}$ is the thermal resistance of the encapsulation.



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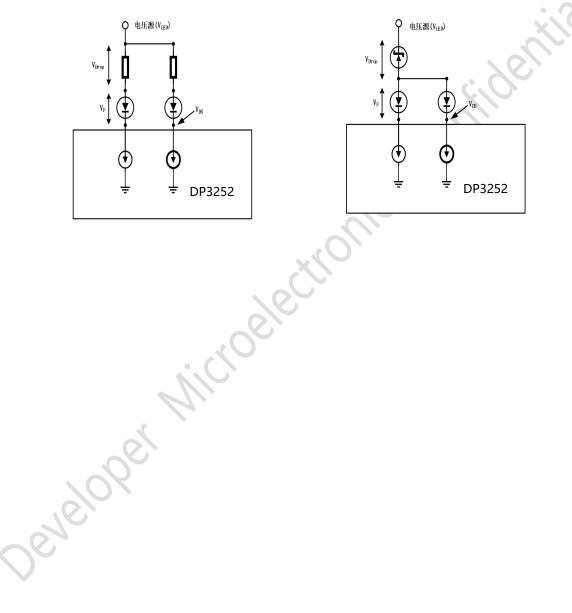
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12 LOAD TERMINAL VOLTAGE(VLED)

In order to optimize the heat dissipation capacity of the package, it is recommended that the best operating range of the output terminal voltage (VDS) is 0.3V to 1.0V(IOUT = 0.5-36mA). If VDS=VLED-VF and VLED=5V, the high output voltage (VDS) may cause PD (act) > PD (max); In this case, it is recommended to use the lowest possible VLED voltage for use, and an external resistor or voltage regulator can also be used as a VDROP. This results in VDS=(VLED-VF)-VDROP, which reduces the input voltage (VDS) value. The application diagram of the external series resistor or voltage regulator can be referred to the following figure.

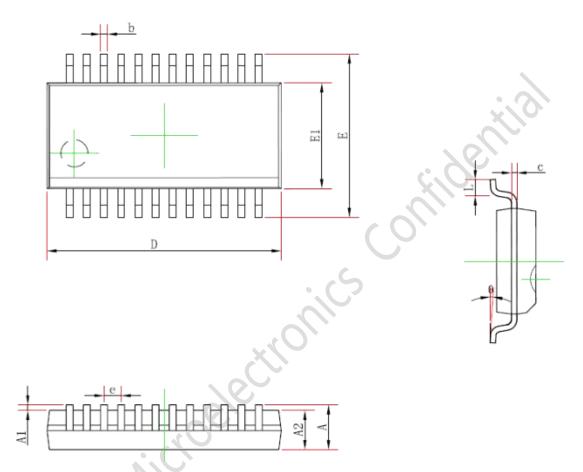


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13 ENCAPSULATION INFORMATION

QSOP24 Plastic Encapsulation Specification Drawing



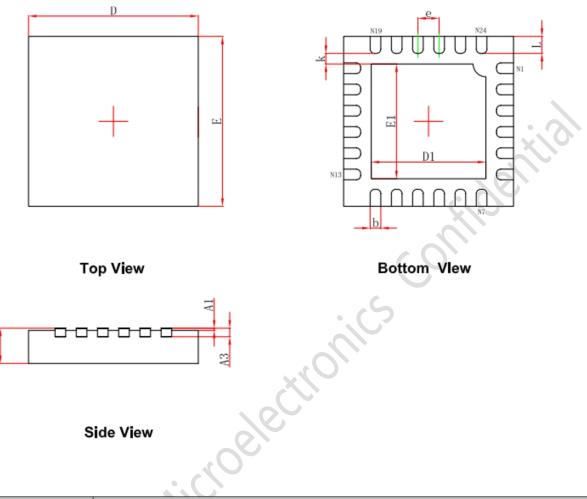
	Millimeters (mm)		
	Min	Мах	
Α	- 2	1.95	
A1	0.05	0.35	
A2	1.05	—	
b	0.1	0.4	
C	0.05	0.254	
D	8.2	9.2	
E1	3.6	4.2	
E	5.6	6.5	
е	0.635TYP		
L	0.3	1.5	
θ	0°	10°	

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QFN24 Plastic Encapsulation Specification Drawing



	Millimeters (mm)		
	Min	Мах	
Α	0.700/0.800	0.800/0.900	
A1	0.000	0.050	
A3	0.203REF		
D	3.924	4.076	
E	3.924	4.076	
D1	2.6	2.8	
E1	2.6	2.8	
k	0.20MIN		
b	0.200	0.300	
е	0.500TYP		
L	0.324	0.476	

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